OpenGL tutorial

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# OpenGL

Computer graphics is an integral part of game programming. The visual content is the way the game communicates with the player.

Specialized computer hardware, the graphics cards, is used to generate all the complex scenes we see in modern games. This hardware has evolved over the years from drawing simple content used in application user interface, to real powerhouses capable of drawing realistic images of complex battle scenes and other physical objects.

Developers need a unified way to communicate with these graphics cards and use their power. Modern operating systems fulfill this through the use of device drivers. The provide the basic operations of text display and line drawing.

Our games though are far more demanding. Complex drawing such as textures, waves, reflections, light and so many other things that make our world so beautiful are required. The graphics cards can perform all these calculations but the effort to develop all the code required would make the development of new games almost impossible.

The solution was given in 1992 with the introduction of OpenGL. The name stands for Open Graphics Library. This is a cross-language programming interface developed by Silicon Graphics. Their aim was to assist computer aided design software to access the hardware of their high-performance workstations.

It offered a unified interface for two- and three-dimensional drawing and was adopted by all the key vendors of hardware and software. It was ported to all the operating systems and is supported by the device drivers of all the graphics cards in the market.

This success has led to a very robust and mature product upon which we can rely and build our games. Many books were written about it and the amount of documentation and examples we can find online makes learning how it works a lot simpler than it used to be.

In this part of the book, we will cover the basics of OpenGL and we will develop a small graphics engine that will allow us to create games using it. We will cover the most fundamental techniques and effects used in game programming.

## Part 1: Basic OpenGL

### The Windows’ window

Before we start building our game infrastructure, we should spend some time to see how an interactive program is made and especially in Windows.

#### The program loop

UI based programs run until the user quits. They constantly ‘read’ the keyboard or any other input device and alter their behavior and response accordingly. This is achieved with an endless loop in which we ‘read’ user input and respond as we can see in the code snippet:

int main(){

// initialize stuff

while (1) {

// read user input

// break if user asks to

// perform any other task

}

// clean up stuff

}

#### Doing it all in Windows

A windows native application must have a function called *WinMain* instead of a *main* function we have for console-based applications.

int WINAPI WinMain(HINSTANCE hInstance, HINSTANCE hPrevInstance, LPTSTR lpCmdLine, int nCmdShow)

The first thing we encounter is the *WINAPI* before the function name. This is a Windows specific convention. It has to do with the way arguments are passed on the stack and who is responsible for cleaning it up at the end.

The parameters of the function are:

* *hInstance* is the handle of the current instance of the program. It is a value assigned by the operating system to identify the program in memory.
* *hPrevInstance* is always NULL. It was used in 16-bit windows.
* *lpCmdLine* the command line of the program
* *nCmdShow* is a flag indicating how the main window will be upon startup.

Here is a sample *WinMain* function:

int WINAPI WinMain(HINSTANCE hInstance, HINSTANCE hPrevInstance, LPTSTR lpCmdLine, int nCmdShow) {

initialize\_application(hInstance, nCmdShow);

// load keyboard shortcuts

HACCEL hAccelTable = LoadAccelerators (hInstance, MAKEINTRESOURCE(IDC\_BASICWINDOW));

// message (msg) variable encodes information about user interaction

// or other system wide event

MSG msg;

// Main message loop:

// waits for user interaction, decodes it, and passes the message (msg)

// to WndProc below

while (GetMessage(&msg, nullptr, 0, 0)) {

if (!TranslateAccelerator(msg.hwnd, hAccelTable, &msg)) {

// let windows process the message

TranslateMessage(&msg);

// ask windows to pass the message to WndProc

DispatchMessage(&msg);

}

}

return (int)msg.wParam;

}

*initialize\_application*: Perform some basic Windows initializations.

*LoadAccelerators*: Load any keyboard shortcuts we may need in our application.

*Main program loop*:

*GetMessage*: wait for user interaction.

*TranslateAccelerator*: check for specific keyboard input.

*TranslateMessage*: convert input to some meaningful stuff.

*DispatchMessage*: pass the input to our message handling function, *WndProc* we see here:

// the callback windows calls when needed via DispatchMessage

LRESULT CALLBACK WndProc(HWND hWnd, UINT message, WPARAM wParam, LPARAM lParam) {

switch (message) {

// menu command

case WM\_COMMAND: {

int wmId = LOWORD(wParam);

// Parse the menu selections:

switch (wmId)

{

// exit menu command

case IDM\_EXIT:

DestroyWindow(hWnd);

break;

default:

return DefWindowProc(hWnd, message, wParam, lParam);

}

}

break;

// draw window contents

case WM\_PAINT: {

PAINTSTRUCT ps;

HDC hdc = BeginPaint(hWnd, &ps);

// TODO: Add any drawing code that uses hdc here...

EndPaint(hWnd, &ps);

}

break;

// destroy the window, here we can do some cleanup

case WM\_DESTROY:

// ok to exit

PostQuitMessage(0);

break;

default:

return DefWindowProc(hWnd, message, wParam, lParam);

}

return 0;

}

This function is our main dispatch mechanism. The system calls it passing it these parameters:

* *hWnd*: the handle of the main window. This is an id assigned by the system to our window upon its creation in the *initialize\_application*­ function.
* *Message*: is the identifier of the event or message
* *wParam, lParam*: are additional information holding the details of the message.

At this point I would like to point how the program terminates. Initially we respond to the message *WM\_COMMAND*, which means that a menu command was selected. In this case the *wParam* parameter holds the menu command ID encoded in the low 16 bits. Using the *LOWORD* C++ macro we isolate the low part of the variable and if the value is equal to exit command ID, we call the *DestroyWindow* system function indicating we want to destroy the window and exit the application. As consequence the system calls *WndProc*, this time with the *WM\_DESTROY*. Our response to that is a zero in our *PostQuitMessage* call. This causes *GetMessage* to return zero and break the main program loop.

### Adding OpenGL

The next step is to create a window that connects with OpenGL to give us access to the advanced drawing it provides.

#### Windows drawing basics

Whenever the system wants to update the contents of our window it sends a *WM\_PAINT* message to our *WndProc* function.

In order to understand what we are doing we need to take a closer look at the way Windows handle drawing. In the *WndProc* we receive a message called *WM\_PAINT*. This tells us that we must update the contents of the window. In our sample we do not do much. There is one thing to notice here. The communication channel between our program and the Windows drawing subsystem. Here is the code fragment for that message:

case WM\_PAINT: {

// details about the command are in this struct

PAINTSTRUCT ps;

// HDC in our telephone line to the video driver

HDC hdc = BeginPaint(hWnd, &ps);

// TODO: Add any drawing code that uses hdc here...

// EndPaint tells the system we are done

EndPaint(hWnd, &ps);

}

break;

The communication channel is called *device context,* and we obtain its ID. You can think of it as a canvas we can draw on, or as a communication line with the graphics driver. This channel is temporary, and it is released with the call to *EndPaint*.

#### Initializing OpenGL window

When we need to use OpenGL, we create our window with a special parameter. We added the *CS\_OWNDC* style to our windows class description. This tells Windows that we want to maintain a permanent channel of communication with video driver. This is a requirement because we will not use the default windows drawing mechanism but instead, we will repaint the screen whenever we want.

We will use OpenGL *double buffering* to have smooth drawing. This is like having two drawing surfaces. We are shown one surface, and we hide the second. All drawing is taking place on the hidden surface and when we are done, we swap them. This presents the scene to the viewer all at once without the drama of rendering object by object, especially when we have animation. The sample that draws with OpenGL is ***basic\_opengl***.

The biggest change we need to make is the creation of the window that does all the drawing. In our case this is the main window of the application. We create our main window and then we perform a series of OpenGL initializations and connections with our window. So, let us try to put things in order and explain what we are doing.

First, we create the window like we do in any Windows application by calling the *CreateWindow*. No surprises so far. The next thing we do is request the communication channel with the drawing mechanism we talked about before. For this we call the *GetDC* system function which returns us its ID. Needless to say that whenever we fail, we abort the whole operation.

Next, we initialize a *PIXELFORMATDESCRIPTOR* variable. This is a struct describing the structure of our desired OpenGL drawing surface. We use this description to see if the drawing channel we got before is compatible with what we want. This is done by calling *ChoosePixelFormat*. If the display is compatible, we are given a non-zero value, which is an index in the array of display modes supported.

We then pass this index to the *SetPixelFormat*, which performs the appropriate setup in the display driver for OpenGL to function. If this is successful, we create a new channel to use for OpenGL drawing based on the system channel we obtained earlier, calling the *wglCreateContext* function.

The last step is to enable this drawing channel by making it the *current* OpenGL drawing channel. We do this by calling the *wglMakeCurrent* function. If it succeeds, we *ShowWindow* as we would do in any other application.

#### Terminating OpenGL window

All these device contexts we used to do our job are valuable system resources and we should release them when we no longer need them. So, upon program exit we call our function *destroy\_GL\_window* instead of calling *DestroyWindow* directly. This function releases the device contexts we created and then destroys the window.

### Modifying the program loop

Now we will modify the main loop of our program to accommodate for OpenGL drawing.

First we will stop using *GetMessage* and use *PeekMessage* instead. This function check the message queue and if a message is pending it behaves like old one. If no message is pending it returns allowing us to perform any tasks we want. Here is how our program loop looks like:

bool bLooping = true;

MSG msg;

while (bLooping) {

// check for windows messages and process them

if (PeekMessage(&msg, NULL, 0, 0, PM\_REMOVE) != 0) {

// destroy window was invoked (escape or Alt-F4)

if (msg.message == WM\_QUIT)

bLooping = false;

TranslateMessage(&msg);

DispatchMessage(&msg);

}

else { // no messages, just loop for next frame

if (g\_window.isMinimized) { // if window is minimized

// yield back to system, do not waste processing power

WaitMessage();

}

else {

// here we do our own processing and drawing

}

}

}

When our program window is not minimized we get on with our processing, otherwise we just pass control to the operating system without wasting any system resources and slowing down other programs.

### Drawing in OpenGL

When we created the main window of our game, we used a *PIXELFORMATDESCRIPTOR* structure. We used the value *PFD\_DOUBLEBUFFER* to initialize it. This means that we have two drawing surfaces for smooth drawing.

From our main loop, first we call our function that does the dirty work of drawing everything, and then we call the *SwapBuffers* function to that displays the contents of the hidden drawing surface.

// render scene

frame\_render();

// Swap Buffers (Double Buffering)

SwapBuffers(g\_window.hDC);

Let us look at the *frame\_render* function and look at our first scene.

void frame\_render() {

// first step: set up our camera

// black background

glClearColor(0.0f, .0f, 0.0f, 1.f);

// clear screen and depth buffer

glClear(GL\_COLOR\_BUFFER\_BIT | GL\_DEPTH\_BUFFER\_BIT);

// set the viewport to the whole window

glViewport(0, 0, (GLsizei)(g\_window.vwidth), (GLsizei)(g\_window.vheight));

// select the projection matrix

glMatrixMode(GL\_PROJECTION);

// reset the projection matrix

glLoadIdentity();

// set the viewing angle to 45 degrees

// set the aspect ratio of the window

// and draw everything between 1 and 1000 units from the viewer

gluPerspective(45.0f, (float)(g\_window.vwidth) / (float)(g\_window.vheight), 1.0f, 1000.0f);

// second step: the world we want to picture

// select the modelview matrix

glMatrixMode(GL\_MODELVIEW);

// reset the modelview matrix

glLoadIdentity();

// move 6.0 units apart

glTranslatef(0.f, 0.0f, -6.0f);

// drawing using triangles

glBegin(GL\_TRIANGLES);

// set the color to red

glColor3f(1.0f, 0.0f, 0.0f);

// top vertex

glVertex3f(0.0f, 1.0f, 0.0f);

// set the color to green

glColor3f(0.0f, 1.0f, 0.0f);

// bottom left vertex

glVertex3f(-1.0f, -1.0f, 0.0f);

// set the color to blue

glColor3f(0.0f, 0.0f, 1.0f);

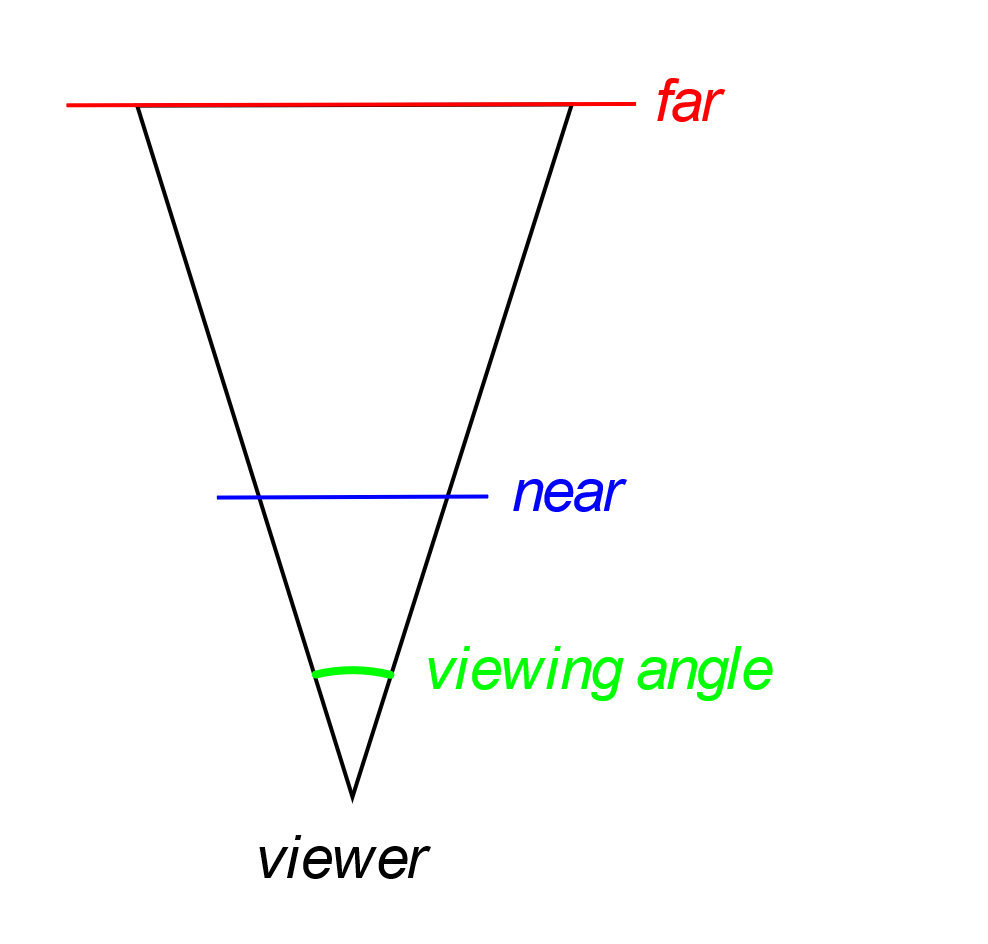
// bottom right vertex

glVertex3f(1.0f, -1.0f, 0.0f);

// finished drawing the triangle

glEnd();

}

This function is made up of two distinct parts. The camera that takes a picture, and the world we want to take a picture of.

The sensor of our camera is our window. In the beginning we clear the camera sensor. OpenGL will automatically remove hidden surfaces and objects. Then we define the portion of the sensor we want to use. Our camera is more capable than any ordinary camera. The next step is to set up our lens. For our sample we have a lens with a viewing angle of , set the aspect ratio of the sensor and tell it to capture anything from one unit to one thousand units from our location. Note here that we are specifying the *nearest* and *furthest* distances, so they are positive. The default position of the camera is at the position , with the up direction being at the , and looking towards the negative .

Figure : The view perspective.

When we are done with the camera, we start describing our objects. OpenGL automatically calculates the transformations and draws everything, taking care of hidden surface removal.

In this sample we draw a simple triangle six units towards the negative of the .

### OpenGL and the transformation matrix

In the second part of this book, we were introduced to matrices and how we can use them to perform transformations and projections. OpenGL uses matrices as well. Here we are going to take a closer look at how it uses them to perform all its calculations.

In OpenGL there is one active matrix for the camera settings, identified as *GL\_PROJECTION* , one for the model world identified as *GL\_MODELVIEW*, and some more that we will see in time. We select them calling *glMatrixMode*, with the appropriate matrix ID. These matrices are initialized to the identity matrix when we call *glLoadIdentity*. From that point on every change is accumulated, so every time we are left with the latest version of the matrix.

In our sample we start with the *camera* matrix, or *projection* matrix as it is called. We set it to identity matrix and then we call *gluPerspective*, to set it appropriately to behave like the camera we have in mind.

A similar operation is performed for the *world*, or *modelview* matrix. First, we set it to identity matrix and then we modify it to move all the objects 6 units apart from the viewer with the *glTranslatef* function. This tells OpenGL where the objects are and then we draw them using coordinates local to them. This allows us to draw similar objects, say boxes, in many locations in a scene, saving us a lot of memory and processing time.

### Keeping track of time

Our perception of the world and events has to do with time. Everything happens at some speed and that is what we need. A car covers some distance at a specific time interval while a free-falling object accelerates at a standard rate. Another thing is the processing speed of different computer systems. In the old days it used to be impossible to play some games on fast computers because they ran like hell. Game programmers were relying on the processing power of the system to keep track of elapsed time and so when you got a faster computer it was impossible to run the game.

This make clear that what we need to make our games realistic is to know how much time has elapsed since the last time we updated our virtual world and advance everything accordingly. Assume that we have a car that moves at 72 kph. That converts to 20 meters per second. So, if our game runs at 100 frames per second we should advance our car 20 cm per frame.

What we need is a precision stopwatch. We will start it before we enter the main loop and query the elapsed time on every iteration. Then we will be able to calculate all the changes in our virtual world based on real time. This will make our game behave in the same way regardless of the processing power of the computer it runs on.

All operating systems provide a high-definition timer. These timers have a precision of fractions of a millisecond. This precision is more than adequate for the purposes of a video game.

In *Windows* we can use the *QueryPerformanceCounter* to get the current time. Keeping track of elapsed time is done like this:

double cg\_timer::get\_elapsed\_time() {

LARGE\_INTEGER qwTime;

// get current time

QueryPerformanceCounter(&qwTime);

// calculate elapsed time since last call

double fElapsedTime = (double)(qwTime.QuadPart - m\_llLastElapsedTime) /

(double)m\_llQPFTicksPerSec;

// remember this call, the variable is a member of the class

m\_llLastElapsedTime = qwTime.QuadPart;

// return elapsed time

return fElapsedTime;

}

In our program we initialize and start the timer before we enter the main loop. In every iteration we just query the elapsed time which we can use in our calculations. Our first attempt to do some time tracking is counting the frames per second our game runs:

// frame counting mechanism

// the higher the frame rate the faster the system

// if frame rate drops below 30 we are in deep trouble

// we should either optimize the program or buy a new computer

static int m\_nFrames = 0; // frame Counter

static float tot = 0; // time counter

tot += fElapsed; // increment counters

m\_nFrames++;

if (tot >= 1.f) // one second reached

{

char txt[200];

sprintf\_s(txt, "GusOnGames, fps:%d", m\_nFrames);

SetWindowText(g\_window.hWnd, txt);

tot = 0; // reset counters

m\_nFrames = 0;

}

### Summary

This was a simple introduction to OpenGL. We have managed to create a solid foundation upon which we will build a more sophisticated graphics engine for our games. In this part we have seen:

* How to create a window for our game
* How to initialize and terminate OpenGL
* The basics about drawing with OpenGL
* A simple introduction to transformations and their accumulation

In the next part we will dive deeper into the transformations and how they are processed.

## Part 2: The pipeline

Modern graphics hardware is immensely powerful and massively parallel. This means that they can perform too many operations per unit of time. All this results in spectacular images in real time. Our games and animations can use all this power and give users a memorable experience.

By organizing our data and the order of operations we can take advantage of the available hardware and maximize its efficiency. We can break, for instance, the job into distinct stages, and then execute the operations in each one in parallel.

This serialization of stages is what OpenGL does to generate the images we see. For added convenience most of these stages are programmable. We can write our own code that will run on the GPU for maximum efficiency and have complete control over the result.

### Walk the pipeline

There are certain steps in the process of generating OpenGL output. We have access to a number of them. Our main tool is the *GL Shading Language*, or *GLSL* for short. Some are fixed processes carried by the system. Here is a brief description of the OpenGL pipeline:

* *Vertex Specification*: The first thing we must do when we program in OpenGL, is to collect our data. An object on the screen is made up of certain attributes. These are the vertices, a.k.a. the points, the edges, and the faces they define, the colors and the textures, or any other attributes we may need.
* *Vertex Shader*: The first actual calculation is the Vertex Shader. The information we collected in the previous step passes through this. The objective of this step is to calculate the final position of every vertex in the scene. This is a good place to put our 3D calculations, since the GPU will execute them.
* *Tessellation*: in this step the primitives are divided into a smoother mesh of triangles. This step is optional.
* *Geometry Shader*: In this step we can further manipulate our primitives. We can break them into smaller ones, organize them differently i.e., convert points to triangles, or even remove some of them. This step is also optional.
* *Vertex Post Processing*: In this stage, OpenGL decides what is in our field of view and what is not. This process is called *clipping*. There is no way we can intervene in this stage.
* *Primitive Assembly*: This stage collects the vertex data into an ordered sequence of simple primitives. It is also an internal stage we cannot modify.
* *Rasterization*: This stage creates fragments. It is a particularly important step of the pipeline.
* *Fragment Shader*: This stage calculates the color of each fragment calculated by the previous step. We can write code in GLSL and manipulate what the user sees. It is optional to do so, but taking in mind the advantages it gives us, it is clear that this is a very good point to add our code.
* *Per-Sample Operations*: This is the last step of the pipeline. In this stage the engine performs some final tests like *Stencil Test, Depth Test* or *Scissor Test*.

### One step at a time

In the previous part we saw a sample program that was throwing some drawing commands to OpenGL. It was a very straight forward and simple solution. On the other hand, looking at the description of the pipeline is quite intimidating. It is a lot of work that must be done to draw a simple triangle on the screen.

This is true, but the benefits are quite significant. Keeping our renderings organized in the way directed by the pipeline results in a much faster program in general. The draw data are stored in the video memory for faster access and the GPU performs most of the calculations in parallel.

### Vertex Specification

As we said before our first step is the vertex specification. By this we mean that we pass our geometry information to OpenGL to store it in the graphics memory.

### Vertex Buffer Objects

**VBO** stands for **Vertex Buffer Object**. This is simply an array of data. The magic with VBOs is that they exist in the graphics card memory and are instantly accessible by the GPU during calculations, freeing the CPU and the system bus.

In order to draw in OpenGL, we must submit a stream of data (usually the vertex coordinates) and then tell OpenGL how to interpret them.

These steps are usually performed when we create an object such as a cube. After we have created the geometry vertices, we ask OpenGL to allocate enough space in the graphics memory and then we store our data in that memory.

Then we set the required parameters of how the data is organized. First we set the number of bytes each point’s coordinates take up in memory and then we provide an array of indices telling OpenGL in which order to read the points.

GLuint create\_vbo(std::vector<float>& vertices, std::vector<unsigned short>& indices) {

// the identifier of the buffer we will create

GLuint vao;

// generate the buffer

glGenVertexArrays(1, &vao);

// and make it current so that any subsequent calls will operate on it

glBindVertexArray(vao);

// we start with the vertex coordinates

GLuint position\_buffer;

// generate buffer

glGenBuffers(1, &position\_buffer);

// make it current

glBindBuffer(GL\_ARRAY\_BUFFER, position\_buffer);

// copy the data into it

glBufferData(GL\_ARRAY\_BUFFER, vertices.size() \* sizeof(float), &vertices[0],

GL\_STATIC\_DRAW);

// set the data organization parameters

glVertexAttribPointer(0, 3, GL\_FLOAT, GL\_FALSE, 0, (void\*)0);

// enable the position data at 'location=0' (see shader!)

glEnableVertexAttribArray(0);

// now set the index buffer

GLuint index\_buffer;

glGenBuffers(1, &index\_buffer);

glBindBuffer(GL\_ELEMENT\_ARRAY\_BUFFER, index\_buffer);

glBufferData(GL\_ELEMENT\_ARRAY\_BUFFER, indices.size() \* sizeof(unsigned short),

&indices[0], GL\_STATIC\_DRAW);

glBindVertexArray(0);

// return the generated buffer ID

return vao;

}

Our data are now saved in the graphics memory and they are ready to be used to draw our objects.

To draw from a *vertex buffer,* we must use the *pipeline* and provide the Vertex and Fragment shader.

#### Structure of the program

In the sample program ***pipeline***, we see a first approach of creating a reusable infrastructure for our games. This will take away a lot of the work in the future as more code will be added to this library.

This program copies the code from the previous example. Window and OpenGL initialization are the same. The program is now made up of two files. In the first file called *common.cpp* we can see the code used for window and library initialization, as well as the *WinMain* function. This code is our first library code. It is code we do not need to change very often.

We may have to add some bits here and there to support our increasing needs. For our current needs I have added the functions *init\_game* and *terminate\_game*. The first is called before we enter the main loop, so we can do our game initialization and the second is called after the main loop to perform any cleanup we need to do.

#### Organizing the data

The first step in the pipeline is the *Vertex Specification*. In this step we gather and organize the data that represent our meshes and models, and we load our shader programs.

This is done in our new *init\_game* function. There the first thing we do is load the shaders into the GPU memory. These little programs will guide the GPU when we render the triangle.

Then we allocate space in the memory of our graphics card and store the triangle geometry and color attributes to be used for drawing. We are starting with the geometry data. The shaders will be examined a little later. For the time being, we compile and load them to get things going.

The first thing we must do is allocate a *Vertex Array* in which we will store our data.

// create the main storage

glGenVertexArrays(1, &vertex\_array);

// bind and use it

glBindVertexArray(vertex\_array);

*glGenVertexArrays* allocates the memory and stores its identifier in the *vertex\_array* variable. OpenGL depends heavily on its state. After we allocate the array, we bind it using *glBindVertexArray*. From that point on subsequent calls are appended to this array. Any other allocations are stored within this array. So, our next step which allocates memory for the vertices of our triangle will allocate the buffer inside the *vertex\_array.*

// create a buffer for the vertices

glGenBuffers(1, &vertex\_buffer);

glBindBuffer(GL\_ARRAY\_BUFFER, vertex\_buffer);

glBufferData(GL\_ARRAY\_BUFFER, sizeof(vertices), vertices, GL\_STATIC\_DRAW);

glVertexAttribPointer(0, 3, GL\_FLOAT, GL\_FALSE, 0, (void\*)0);

glEnableVertexAttribArray(0);

This allocated buffer is inside the vertex array and after we bind it *glBufferData* copies the vertex coordinates inside the *vertex\_buffer*.

OpenGL buffers can contain more than just data. They can also store commands like *glVertexAttribPointer* which instructs the library where to ‘find’ the data. Storing these commands within the vertex buffers speeds the drawing process dramatically. You can visualize the buffers as programs containing both data and code that are stored in superfast GPU memory and run int GPU as well.

Similarly to the vertex data we allocate buffer for the colors. We can add buffers containing any information we like. The most common attributes are colors, textures coordinates and normal vectors.

#### Vertex shader

As we know from everyday experience, what we see is subject to our location, the direction of our sight, the objects’ location, and orientation. On the other hand, every object can have its own coordinate system and it have its geometry expressed based on that system.

This is the way we define objects in 3D handling software, be it Computer Aided Design or Game software, or any other kind of software of which we can think.

It is the responsibility of the *Vertex Shader* to translate the local coordinates of the vertices to real world coordinates and then to view coordinates to draw the object.

The shader can take as input the transformation matrices for the view and for the objects along with the coordinates and other attributes of the vertices. The transformation matrices and the coordinates are used to calculate the final location of the vertices on the screen. Here is the sample shader:

#version 410 core

// input to the vertex shader

// location where the vertex coordinates are stored

layout(location = 0) in vec3 aPos;

// location where the vertex color is stored

layout(location = 1) in vec3 aCol;

// 4x4 matrix for the model

uniform mat4 model;

// 4x4 matrix with the view parameters

uniform mat4 view;

// output of the vertex shader

// the vertex color is passed to the fragment shader

out vec4 vs\_color;

// 'main' the entry point to the shader

void main(){

// calculate the final position for the vertex

gl\_Position = view \* model \* vec4(aPos, 1.0);

// the vertex color

vs\_color = vec4(aCol, 1.0);

}

The first line defines the minimum OpenGL version requirement, which is 4.1 in this case.

Then we describe how our *vertex array* is organized. The first buffer contains the vertices in a three-dimensional vector, and the second contains the colors again as three-dimensional vectors.

The next two variables are the transformation matrices to use. One for the model positioning and orientation, and one for the ‘camera’ transformation.

Finally, we define our output variable *vs\_color* that we are going to use so we can pass the user color to the *fragment shader*. More on this shader when its time comes. Now let us focus on what *vertex shader* does.

OpenGL has some built in variables we can set. One such variable is *gl\_Position*. In this variable we set the final position of the vertex. Here we multiply the view matrix with model matrix and the vertex position. The matrices must be organized column major because this is the convention in OpenGL.

The final variable we set is *vs\_color* which is used to read the color from the vertex attributes and pass it to the next step.

In our program we introduced some new code to handle our requirements in mathematics. The code is in the ‘math’ files. the first thing we introduced is the 4x4 matrix. We need this for the transformations we are going to use in this sample.

mat4 view = perspective\_matrix(pi / 4.f, (float)(g\_window.vwidth) / (float)(g\_window.vheight), 1.f, 1000.f);

mat4 model = translation\_matrix(0,0,-6);

// use shader

glUseProgram(shaderID);

set\_mat4(shaderID, "model", (cg\_float\*)model);

set\_mat4(shaderID, "view", (cg\_float\*)view);

// draw the triangle (vertex coordinates are in the shader)

glBindVertexArray(vertex\_array);

glPolygonMode(GL\_FRONT\_AND\_BACK, GL\_FILL);

glDrawArrays(GL\_TRIANGLES, 0, 3);

glBindVertexArray(0);

The first matrix represents the camera like the call to *gluPerspective* we saw in the previous example, and the second is the translation matrix which is equivalent to the *glTranslatef* call. We pass these matrices to the shader, before we start drawing, giving them the variable names we set earlier in the shader.

#### Fast forward

Now we are going to skip a step or two and jump directly to the *Fragment Shader*. This will let us see how to draw a colorful triangle like the previous example. As we see in the paragraph above. we just set the transformation matrices and then ask OpenGL to draw. Here is the *Fragment Shader*.

#version 410 core

out vec4 color;

in vec4 vs\_color;

void main(){

color = vs\_color;

}

The output of this shader step is the color OpenGL can use for the fragment. So, we just declare an output variable and we call it ‘color’. Now remember the ‘vs\_color’ variable we declared as the output of the *vertex shader*. Here we declare the same variable, only this time it is an input variable. So, we read the color passed to us by the vertex shader and then we pass it to OpenGL. We need to do this because only the vertex shader has access to the vertex array and its contents.

### Tessellation

*Tessellation* is the process of breaking up a large area into smaller pieces. This is what we do when we apply small tiles on a large surface. In computer graphics we divide a large polygon, usually a triangle, into smaller ones.

This process is particularly useful when we want to apply higher detail to objects that are closer to the viewer, while those that are further away do not need high detailed drawing.

Tessellation follows the vertex shader, and it is done in three steps.

The first of the three tessellation phases is the *tessellation control shader*. This shader takes its input from the *vertex shader* and is primarily responsible for two things: the determination of the level of tessellation that will be sent to the tessellation engine, and the generation of data that will be sent to the tessellation evaluation shader that is run after tessellation has occurred.

Second is the *Tessellation Engine* that generates the new vertices. It is a fixed function engine, and we can only set its parameters in the *tessellation control shader*. it produces a number of output vertices representing the primitives it has generated. These are passed to the tessellation evaluation shader.

Third and last step of the process is the *tessellation evaluation shader*. The tessellation evaluation shader runs an invocation for each vertex produced by the tessellation engine. When the tessellation levels are high, the tessellation evaluation shader could run an extremely substantial number of times. For this reason, you should be careful with complex evaluation shaders and high tessellation levels.

First. We create a simpler *vertex shader*. The new one just reads the model coordinates and passes sets them in the OpenGL variable *gl\_Position*. The view and model matrices will be applied in the last step of *tessellation evaluation*.

#version 410 core

layout(location = 0) in vec3 aPos;

void main(){

gl\_Position = vec4(aPos, 1.0);

}

Here are two simple shaders that we can use to tessellate a simple triangle:

// first is the control shader

#version 410 core

layout(vertices = 3) out;

void main(void) {

if (gl\_InvocationID == 0) {

gl\_TessLevelInner[0] = 3.0;

// number of tessellations on each of the outer edges

gl\_TessLevelOuter[0] = 3.0;

gl\_TessLevelOuter[1] = 3.0;

gl\_TessLevelOuter[2] = 3.0;

}

gl\_out[gl\_InvocationID].gl\_Position = gl\_in[gl\_InvocationID].gl\_Position;

}

// second is the evaluation shader

#version 410 core

layout(triangles, equal\_spacing, cw) in;

uniform mat4 model;

uniform mat4 view;

out vec4 es\_color;

void main(void) {

vec4 pos = (gl\_TessCoord.x \* gl\_in[0].gl\_Position) +

(gl\_TessCoord.y \* gl\_in[1].gl\_Position) +

(gl\_TessCoord.z \* gl\_in[2].gl\_Position);

es\_color = vec4(gl\_TessCoord,1);

gl\_Position = view\*model\*pos;

}

More on tessellations when we talk about level of detail in scenes. This is just an example of how it attaches in the pipeline.

#### The Fragment Shader

OpenGL has finished rasterizing the image. That means the image is ready pixel by pixel. It knows what each pixel on the screen represents in terms of objects depth and orientation. This is our last chance, based on knowing what we need to draw, to tell OpenGL what color to set for each pixel.

We created a *fragment shader* before talking about tessellation. There we set the pixel color. Now we are asked to set the pixel color for a tessellated object. For this reason, we calculated the color in the *evaluation shader*. There we had access to the coordinates generated by the tessellation engine. We used that information to calculate a color and create a fancy result.

#version 420 core

out vec4 color;

in vec4 es\_color;

void main(void) {

color = es\_color;

}

### Summary

In this part we saw the steps of the rendering pipeline. It is important to understand how the pipeline works and utilize it to the maximum to get the best results both in image quality and speed of execution.

Here are the steps of the pipeline once again:

* Vertex specification
* Vertex shader
* Tessellation
* Geometry shader
* Vertex post processing
* Primitive assembly
* Rasterization
* Fragment shader.
* Per-sample operations

## Part 3: Shaders and Shader Language

In this part we will cover the *shaders* and the *shader language GLSL*. Shaders are fundamental in OpenGL. They are the tool to take advantage of the graphics hardware that is specifically designed and optimized to perform all the operations required for all the effects we need in our games.

As we have seen in the previous part after we organize our data the control goes to OpenGL and the underlying hardware. Using shaders is the key to fast and eye-catching graphics that will make our games stand out.

### The language

The *language* we use for shaders is GLSL. Its syntax is based loosely on the C programming language. Here is a simple shader program:

#version 410 core

uniform mat4 view;

in vec4 color;

out vec4 vs\_color;

void main() {

vs\_color = color;

float f = 2.0f;

vec4 v = vec4(1,2,3,4)

}

As we can see, statements are quite simple and easy to understand and write. We can create blocks of code by enclosing the statements in curly brackets. The syntax is quite easy to understand if you have some experience with C or C++.

Since the language is so close to the C/C++ syntax we will just do a brief pass over its features.

### The Preprocessor

Just like C/C++ GLSL has a preprocessor. It takes the input shader code and modifies it according to the command we issue. Here is the list of the preprocessor commands:

*#version*: this command must be in the first line of the code. It instructs the compiler to stick to a certain version of the language. This means that the compiler will throw an error if it encounters a feature not supported by the specified version.

*#extension*: used to enable or disable an OpenGL extension that is not yet part of the core implementation of OpenGL.

*#pragma*: allows compiler control. We can use it to enable or disable optimizations or debug mode compile.

*#error, #define, #undef, #if, #ifdef, #ifndef, #else, #elif, #endif*: are the same as in C/C++ and need no extra explanation.

#version 410

#extension ARB\_explicit\_attrib\_location : enable

#pragma optimize(on)

#pragma optimize(off)

#pragma debug(on)

#pragma debug(off)

#error Some error occurred

#define MY\_VALUE 2

#undef SOME\_VALUE

#ifdef MY\_VALUE

#ifndef SOME\_VALUE

#if MY\_VALUE == 3

#else

#elif MY\_VALUE == 4

#endif

### Data types

This is a topic that needs a thorough approach. GLSL introduces some data types we do not have in C/C++. These data types are required to handle the geometry of objects and the transformations that must be applied. Here is the list of data types in GLSL.

* *bool*: Boolean, only *true* or *false*
* *int*: Integer value, *negative* or *positive* value
* *uint*: *Positive integer* value
* *float*: *floating point* number
* *sampler*: this type represents texture sampling; it can be one of these.
  + *sampler1D*
  + *sampler2D*
  + *sampler4D*
* *vectors*: built in vectors of 2, 3, or 4 elements, based on the type of the elements they can be.
  + *bvec2, bvec3, bvec4*: vectors of Booleans
  + *ivec2, ivec3, ivec4*: vectors of integers
  + *uvec2, uvec3, uvec4*: vectors of unsigned integers
  + *vec2, vec3, vec4*: vectors of single precision floats
  + *dvec2, dvec3, dvec4*: vectors of double precision floats
* *matrices*: matrices in GLSL are always made of floating-point numbers either of single or double precision. The latter takes the prefix ‘d’.
  + *square matrices*: these can be 2x2, 3x3 or 4x4 matrices.
    - *mat2, dmat2*: 2x2 matrix
    - *mat3, dmat3*: 3x3 matrix
    - *mat4, dmat4*: 4x4 matrix
  + *arbitrary matrices*: these matrices can be 2x3, 2x4, 3x2, 3x4, 4x2, 4x3. The first number refers to their columns and the second to their rows.
    - *mat2x3, mat2x4, mat3x2, mat3x4, mat4x2, mat4x3*
    - *dmat2x3, dmat2x4, dmat3x2, dmat3x4, dmat4x2, dmat4x3*

All the matrices in OpenGL are column major. That means that in a 4x4 matrix for example the first four elements are those of the first column. One more thing we must keep in mind is that when we talk about the dimensions of a matrix, the first number is the number of columns.

### Arrays

Vectors and matrices are collections of numeric data organized in certain ways, based on the mathematical concepts behind them. If we want collections of data of arbitrary size we need arrays. Arrays in GLSL are declared like arrays in C++.

int indices[5];

vec3 vertices[] = {vec3(0,0,0), vec3(1,1,1), vec3(2,2,2)};

Accessing the elements in an array is similar as well.

vec3 pos = vertices[1];

indices[2] = 3;

### Vectors

Vectors are an important and flexible data type in GLSL. They can be used to access vertex positions, normal vectors, colors, and textures. Vectors can be found anywhere in the shader programs we create and can help us accomplish complex tasks.

First let us see the members of the vector type.

* {x, y, z, w}, used when accessing position data.
* {r, g, b, a}, used when dealing with colors.
* {s, t, p, q}, used for texture coordinates.

*vec2* has only the first two members, *vec3* the first three, and *vec4* has them all. We can access them either using the index of their position in the vector, or using the corresponding name:

If is a vector, is equivalent to and and . Be careful though because if is a , then is not defined and will yield an error.

Accessing the elements of a vector using their names is very flexible. Let us assume that is a vector of type . Here is what we get when accessing its members:

* *v.x*: yields a floating-point number
* *v*.xy: yields a *vec2.*
* *v.yzx*: yields a vec3 initialized like this {v.y, v.z, v.x}
* *v.yxwz*: yields a reordered vec4.
* *v.xyxy*: yields a vec4 based on *x* and *x* and *y* elements.

It is obvious that there are numerous combinations we can have when accessing the elements of a vector.

Another thing worth mentioning is the initialization of vectors. The language accepts many combinations of vectors, and values:

// initialize a vector with floats

vec2 v = vec2(1, 2);

// initialize using another vector and float

vec3 u = vec3(v, 1);

// or using a float and a vector

vec3 u2 = vec3(1, v);

// use part of u and v

vec4 t = vec4(u.xy, v);

// use x of u for all of t elements

vec4 t = vec4(u.xxxx);

// use 1 for all of the elements

vec4 t2 = vec4(1);

// member access can be used to set values as well

t2.xy = t.zw;

We can use another vector to initialize one, or if the vector we use is short we can fill in with another vector or values. The only limit to the combinations we use is the actual problem we are trying to solve and the data we have available.

### Matrices

We have cleared that matrices in OpenGL are column major, so is a vector of the elements of the first column. Its length depends on the number of rows in the matrix.

vec2 v = vec2(1, 2);

vec3 u = vec3(v, 1);

mat4 m;

m[0] = vec4(v, 2, 3);

m[1][0] = 5;

m[2] = vec4(u.xy, v);

### Operations between matrices and vectors

We said earlier that vectors can be used to represent vertex positions and matrices can hold transformations. In this section we will see the operations we can do with vectors and matrices to do all the calculations we need.

Here is a sample code snippet with the operations we can do:

mat3 t, r; // translation, rotation

vec3 v, u; // two vectors

float f; //

// assume the variables are initialized

u = f \* v; // scaling vector v

// or

u = t \* v; // translate v

// or

u = r \* v; // rotate v

// or

// translate and then rotate v

u = r \* t \* v;

// setting the final location of *vertex\_pos*

// using *view* and *model* matrices set by our program

gl\_Position = view \* model \* vertex\_pos;

Just a little reminder here. As we saw in part 2, although matrix multiplication is performed from left to right, the results propagate from right to left. So, when we perform the operation , we end up applying translation and the rotation.

### Flow control.

GLSL, like any other language, supports flow control of the code depending on conditions. Being modeled after the C programming language means that whatever we present here is like thing we already know from our experience with C++, which is based on C to ease transition.

In GLSL we have *if/else* and *switch* to direct code execution based on conditions.

in int a\_variable;

out vec4 s\_color;

void s\_conditional() {

if (a\_variable == 2) {

gl\_Position = vec4(1, 2, 3, 4);

s\_color = vec4(1, 1, 1, 1);

}

else {

gl\_Position = vec4(4, 3, 2, 1);

s\_color = vec4(1, 1, 1, 0.5);

}

// or

switch (a\_variable) {

case 1: // set color to white

s\_color = vec4(1, 1, 1, 1);

break;

case 2: // set color to red

s\_color = vec4(1, 0, 0, 1);

break;

case 2: // set color to green

s\_color = vec4(0, 1, 0, 1);

break;

default: // set color to blue

s\_color = vec4(0, 0, 1, 1);

break;

}

}

### Loops

GLSL supports the three basic loops we know. These are the *for, while,* and *do/while* loops. Whatever we said about these loops when we were introduced to them in C++ is valid for GLSL loops as well. They behave in the same way. *for* and *while* loops perform the check in the beginning of the loop, while the *do/while* loop performs the check at the end. This means that the first two may never enter the code inside the loop, and the third will execute that code at least once.

Their syntax is the same as in C/C++ we know already:

void loops() {

for (int i = 0; i < 10; i = i + 1) {

// do something

}

int j = 0;

while (j < 10) {

// do something

j = j + 1; // remember to increase counter!

}

int j = 10;

do {

// do something

j = j - 1; // remember to decrease counter!

} while (j > 0);

}

### Structures

As we saw in C++ structures are custom data types. They give the opportunity to put together data describing one entity.

struct my\_vertex {

vec3 pos; // position

vec2 tex; // texture coordinates

vec3 normal; // normal vector

};

// here we have an array of structures

my\_vertex mv[10];

mv[0].pos = vec3(1, 1, 1);

// initializing an array

my\_vertex v = my\_vertex(vec2(0, 0, 0), vec2(1, 1), vec3(1, 0, 0));

We see that GLSL structures are simple, and they do not defer much from C++ structures. Declaring, accessing, and initializing a structure is modeled after the simplest versions of their C/C++ counterparts.

### Functions

Now is the time to see how we can organize our shader code into meaningful and reusable blocks. As in C/C++ functions can take arguments and return values.

Let us start with the entry point to our shader. The first function of our shader called by the system is as you may have guessed the *main* function. This function takes no arguments and returns nothing.

Our shaders are supposed to perform whatever calculations we need and finally set predefined OpenGL variables that will be used to create the scene. Here is a *main* function that sets the final position of a vertex:

void main(){

gl\_Position = vec4(aPos, 1.0);

}

As we do in any programming task that is complex and big, putting all the code in one function is not a clever idea. The following example shows how we can use a function that takes a direction vector and returns a new direction.

vec3 redirect(vec3 dir) {

// this might be the result of a complex calculation

return vec3(-dir.x, dir.y, dir.z);

}

We have seen the benefits of creating and using functions when we talked about the subject in C++.

There are many built-in functions in GLSL to assist us in developing our code. These include trigonometric functions, logarithmic and exponential functions, common mathematical functions, geometric functions, relation and logical functions, and texture functions. Appendix A has a list of the built-in GLSL functions.

### Shader input and output

Data defined by our application is input for the shader. The shader performs some calculations and then outputs the results.

The *vertex shader* for example, accepts as input the vertex coordinates and converts them into clip coordinates, using view and model transformations, for the *fragment shader* to use.

#### Input variables.

Shaders know nothing about our world. They are great at exploiting the graphics hardware and performing complex calculations. We can layout our vertex data and attributes so that OpenGL can pass them to the shader.

Input variables to the shader, are declared with the keyword *in*:

in vec4 color;

Our first job is to ‘tell’ the shader how our data is organized. Let us assume that our vertex has its coordinates organized as a three-dimensional vector. For this information se are creating a variable of type *vec3*. As we saw in the previous part this information is the first we put in the *vertex array.* This is accessed by the shader with a *layout qualifier*. The *layout qualifier* specifies where the variable is stored within the *vertex array*.

To read the coordinates of the vertex we will create a variable of type *vec3* and call it *aPos*. To read the actual vertex data we must use the *layout qualifier*.

layout(location = 0) in vec3 aPos;

This means that in the first *buffer* of the *vertex array* and in the form of a *vec3* structure we have stored the vertex coordinates. Remember how we set up the vertex data:

// create a buffer for the vertices

glGenBuffers(1, &vertex\_buffer);

glBindBuffer(GL\_ARRAY\_BUFFER, vertex\_buffer);

glBufferData(GL\_ARRAY\_BUFFER, sizeof(vertices), vertices, GL\_STATIC\_DRAW);

glVertexAttribPointer(0, 3, GL\_FLOAT, GL\_FALSE, 0, (void\*)0);

glEnableVertexAttribArray(0);

OpenGL knows how to ‘*walk’* through our data and set the data pointers correctly, and now our shader knows how to read that data.

The vertex sampler can have similar input, the texture coordinate of the vertex. This information must be passed to the fragment shader. We will see how the vertex shader outputs the information in the next section, now we are interested in how the fragment shader reads it. Reading input requires the *in* directive at the variable declaration. Variables that are passed from one step to the other do not require the *layout qualifier*.

in vec2 texCoord;

Another type of input mechanism is the *uniform*. With this we pass names variables of any type we need to the shader. A *uniform* is a global storage location that is accessed by its name. we can write data to it from our C/C++ code and then read that data in our shader.

We use the *glUniform* family of functions to write to a location. In our ***pipeline*** example we pass the camera matrix like this:

glUniformMatrix4v(glGetUniformLocation(program,"view"), 1, GL\_FALSE, viewmat);

And then we read it in our shader like this:

uniform mat4 view;

*Uniforms* are accessible in all stages of the pipeline.

#### Output variables.

As we have said, shaders must generate some output. This either by setting OpenGL internal variables like vertex position in clip coordinates, or by setting variables for the next step in the pipeline.

*gl\_Position* is a built-in function in OpenGL that holds the vertex location after we have finished our calculations about it. A list of the built-in functions can be found in Appendix B.

Here we are going to examine the second type, the variables passed to the next step. They are preceded with the keyword *out*, letting the compiler generate the code to link this variable with the next step. To complete the example of the previous section, where we needed to read the vertex texture coordinate in the vertex shader and pass it to the fragment shader, here is how we output the variable:

out vec2 texCoord;

### Summary

In this part we did a brief pass over the OpenGL Shading Language. Our main objective was to get the basics of the language. Its features will be explained in depth in the next parts as we will study the techniques used for the various visual effects.

## Part 4: Drawing simple objects in 3D.

The two parts that went before gave us some clues as to how to draw in OpenGL. We can create a window for our game and draw a simple tringle inside it. We can even use shaders and vertex arrays to store our data in the video memory so that the GPU can access it faster and speed up drawing.

The next step is to start creating solid objects on three dimensions. We must learn how to draw them and create some realistic three-dimensional effects.

We must also be clear how player vision works. Understand the mathematics behind the camera and its lens. How to handle the zoom and the field of view. What is the effect of camera position, orientation, and view direction?

For the needs of this book, I have created the ***atlas*** game engine. It is not a production game engine, although it can be used for some simple games. Yet it has all the key components and architecture to be used as a tutorial of how games can be made.

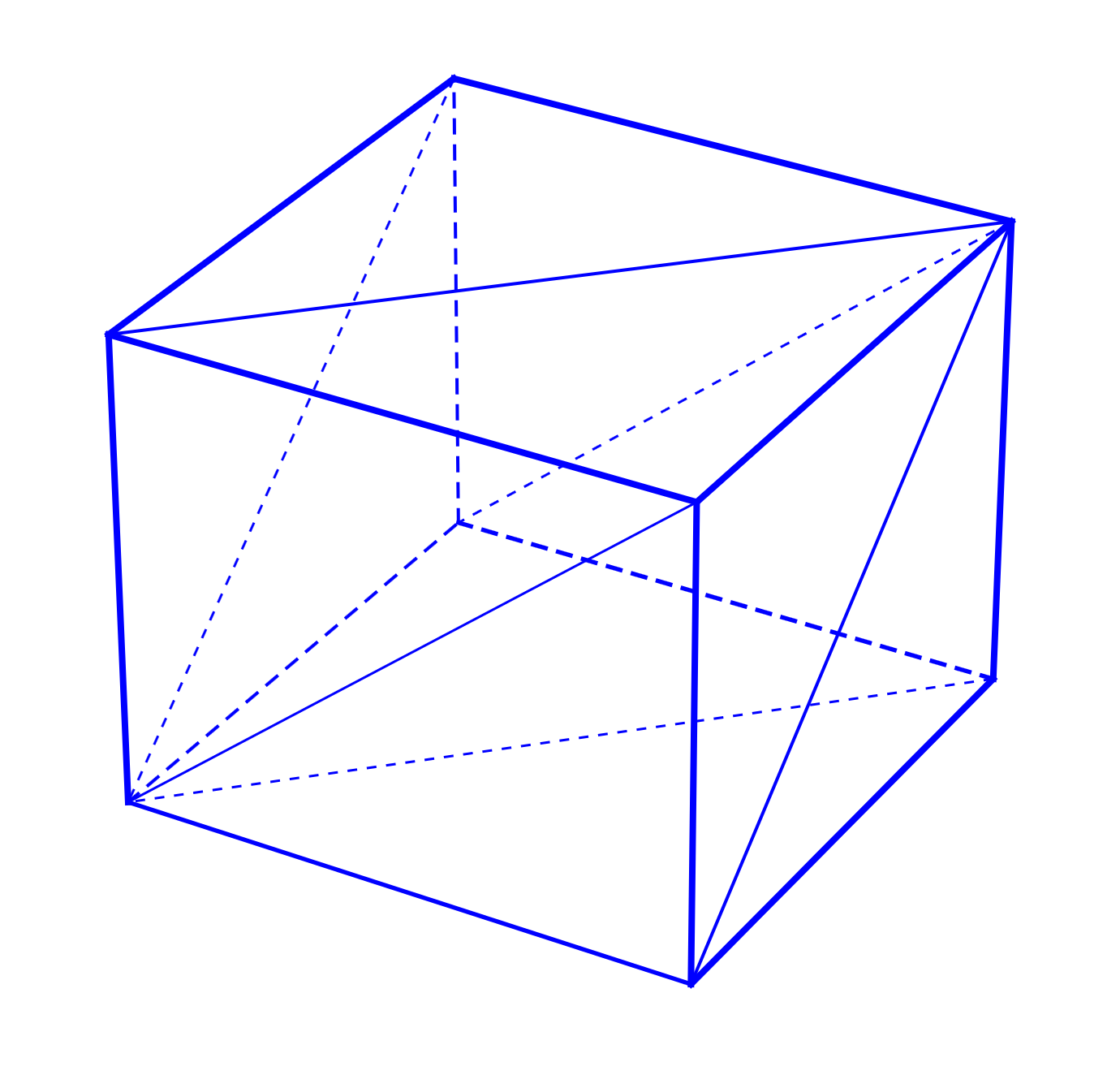
The first two components of the engine we need are the ***graphics*** and the ***math***. The first has all the Windows and of course the OpenGL functionality we need, and the second the mathematics to support all our work.

We name the types as the *shading language* to make reading of the code easier. We did not use the ***glm*** library because it is big and harder to browse through the code.

The other components of the engine will be discussed in time when we need them as we proceed with our journey in game development.

You can download the game engine along with all the examples for this book from GitHub. The link to the repository is <https://github.com/cosfer65/ogl_tutorial>.

### The 3d mesh

A mesh is a collection of *vertices, edges,* and *faces*. A line between two vertices is an edge, and a closed polygon is a face. The polygons can be triangles, quadrilaterals or any convex or concave polygon. In game programming we prefer triangular meshes because they are simpler to render.

Meshes represent the surface and the volume of 3D objects. So, we use them in our games to draw our objects or to check for collisions.

The ***math*** library in the ***atlas*** engine is based on triangular mesh to represent any solid object. This simplifies drawing and unifies our calculations.

Figure : A meshed cube

### An eye to the word

Before we go any further we should have some basic understanding about the way OpenGL defines and handles what we see and how.

As you might expect, starting with view definition in OpenGL is not that hard. Figure 3 shows the view volume as defined in OpenGL.

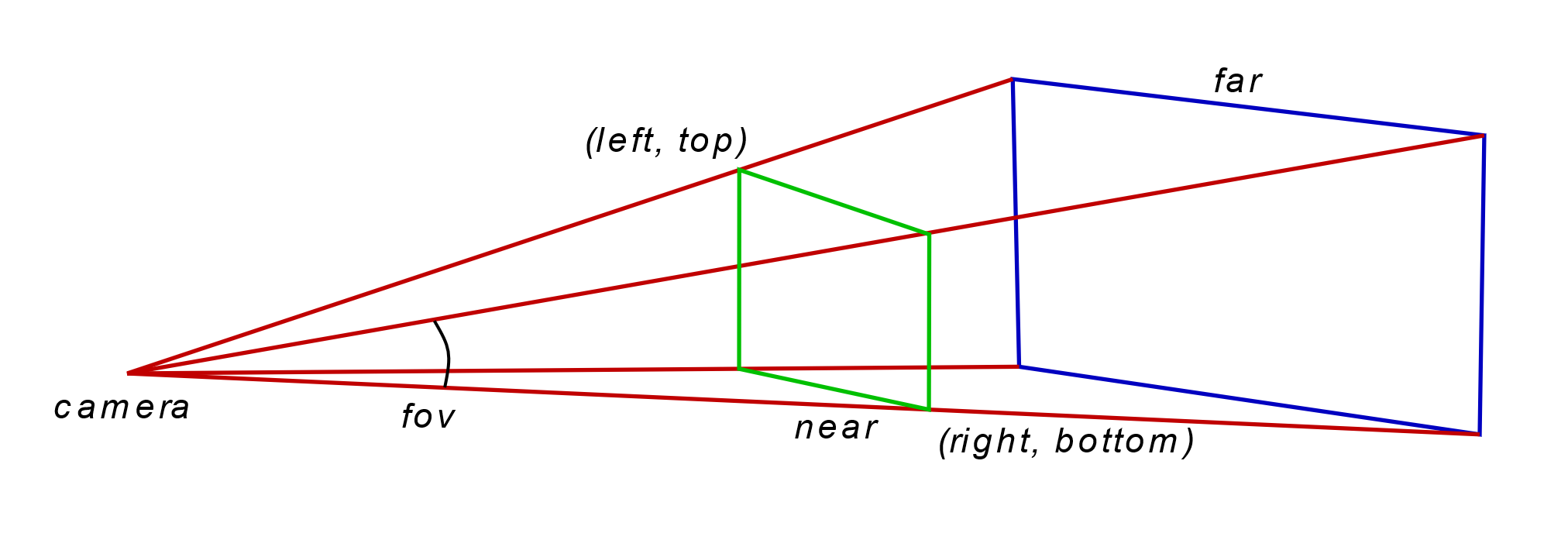


Figure : The OpenGL view volume

The camera is actually the position of the viewer. The field of view is a cone, but because the screen is rectangular it is cropped to form a pyramid. In OpenGL we must define the fov (field of view) angle, the aspect ratio of the width and height of the display window, the *(left, top)* and *(right, bottom)* points, the distance of the near plane (marked in green) and the distance of the far plane (blue). Anything closer to the viewer than the near plane, or further than the far plane is not rendered.

The geometric solid that defines the view volume is a frustum because it is part of a view cone (pyramid if we want to be precise). It is the shape of the computer screen that defines a pyramid, and this is the reason we talk about frustum but draw and calculate a pyramid.

#### The viewport projection matrix

The dimensions of the *view window* and the *near* and *far* distances are used to form what we call the *frustum matrix* or *viewport matrix*.

There is a function for this purpose in the ***math*** library. It is in the file *cg\_matrix.cpp* and this is its prototype:

void frustum\_matrix(cg\_float\* matrix, cg\_float left, cg\_float right, cg\_float bottom,

cg\_float top, cg\_float znear, cg\_float zfar);

The *left-top* and *right-bottom* points hardly make any sense to humans. We can better understand the angle indicating the *field of view*. This is a metric completely independent of the view distance. If you notice camera lenses and zoom are also measured by this angle. Focal length of a lens is actually a function of this angle.

The *cg\_viewport* class which handles the viewport specifics in the ***graphics*** library has the function *set\_fov* which sets this angle. Notice that the angle is in the vertical axis and not in the horizontal.

Having this angle, it is a matter of simple trigonometry to calculate the two corner points and build the transformation matrix for the projection.

#### The camera matrix

Setting the viewport is independent of the location we are standing, the direction we are looking at, and our orientation. These parameters are moving the view volume around bringing objects in and out of view.

We can use three vectors to handle the camera. The first vector will hold the actual location of the camera, the second the point we are targeting, and the third will point to our *UP* direction.

All this is handled by the *cg\_camera* class. It requires the three vectors we just described and returns us the corresponding transformation matrix by calling the *perspective* function.

The first thing we do when initializing the game is create a viewport and camera object to handle the way we see the world.

### Shading things

As we saw in *Part 3* the best practice when drawing in OpenGL is to exploit the GPU and use the pipeline writing some shaders.

The shaders we are going to use for the time being are quite simple. Our primary goal is to explain how to handle the basic transformations in three dimensions. Drawing a simple triangle as we did before is not enough to master OpenGL.

So, for our first real 3D drawing we are only using a *vertex* and a *fragment* shader. The first is used to calculate the transformations of the vertices and the second to set the drawing color.

The ***graphics*** library supports reading the shaders from external files and this is how we use them here.

These are quite simple shaders so we can go with OpenGL version 3.3.

// vertex shader

#version 330 core

// vertex position in local coordinates

layout(location = 0) in vec3 aPos;

// camera has the combined viewing matrix

uniform mat4 camera;

// model has the combined matrix of object position and orientation

uniform mat4 model;

void main() {

// calculate final vertex position in the 3D space

gl\_Position = camera \* model \* vec4(aPos, 1);

}

// fragment shader

#version 330 core

// drawing color for OpenGL to use

out vec4 color;

void main() {

color = vec4(1, 1, 1, 1);

}

The only thing we need to pay attention to is the *vertex shader* which calculates the final position of the vertex. The *camera* matrix is the combined projection matrix for the *viewport* and the *camera*.

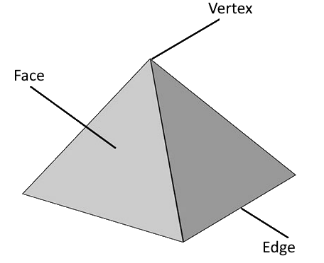
We pass a combined matrix for speed reasons. This shader is called for every vertex, and if the scene has many complex objects it will be called thousands of times. So, it is better to save a matrix multiplication and perform it only once instead doing it for every vertex.

Take a good look at the *fragment* shader. In this sample it is just setting the drawing color to white. Here is the point where most of the visual effects take place. It will get more complex as we add effects.

### Creating a simple solid

In the beginning we are going to create a cube and a sphere. They are among the simplest solids and they are very good to show animation and other techniques, like textures, shadows etc.

As mentioned earlier, the base of all solid objects is the *mesh*. When we create our objects the library generates a mesh. This mesh can be used later for all physics related calculations. But for the time being we will stick to the mesh and how to use it in OpenGL.

When we create a *cg\_gl\_cube* the ***graphics*** library creates a mesh to represent the cube. To accurately display a mesh, we need three things. The first element is the *vertices* of the mesh, the second element is the *normal vector* at each vertex and finally the order in which to access the vertices that represent the faces of the mesh and draw them. Our implementation contains one extra element the texture coordinates.

A grey and red geometrical object

Description automatically generatedNormal vectors will be used later when we add lighting and texture coordinates when we add textures. Right now, we are drawing in wireframe mode because drawing without light generates a flat monochrome image.

Solid objects can be moved and rotated. For this reason, they have two member variables of type *vec3*, the *position* and the *rotation*. We are using *Euler angles* for the rotation and not *quaternions* to keep things simple. In the *frame\_move* function we move our objects. The function takes as input parameter the elapsed time since it was last called. In the first part we touched the subject of keeping track of time. As you can see in the code the elapsed time plays a significant role in the object movement as the amount of movement depends on it and the ‘speed’. We change their angle around one or more axes. The cube is rotated around all three of its axes while the sphere is only rotated around its vertical axis.

### Drawing the objects

In our frame\_move function we moved our objects. The movements simply change the value of their internal variables. These values control their position and orientation in our virtual world. We must pass them to OpenGL to render them correctly.

This is done in the *frame\_render* function. First we create the *camera* matrix from the view and camera parameters. Then we activate the simple shader for wireframe drawing and draw our objects. This is all we care about for now. The rest will be covered in the next section.

virtual void frame\_render() {

// set the viewport to the whole window

m\_view->set\_viewport();

// clear screen

glClearColor(.5f, .5f, .5f, 1.f);

glClear(GL\_COLOR\_BUFFER\_BIT | GL\_DEPTH\_BUFFER\_BIT);

// combine the view and camera matrices into one

mat4 cam\_matrix = m\_cam->perspective() \* m\_view->perspective();

// enable the shader

m\_shader->use();

// set the combined view matrix

m\_shader->set\_mat4("camera", cam\_matrix);

// draw the objects

simple\_cube->render(m\_shader);

simple\_globe->render(m\_shader);

// enable the texture shader

mt\_shader->use();

// set the combined view matrix

mt\_shader->set\_mat4("camera", cam\_matrix);

// activate the texture engine

glActiveTexture(GL\_TEXTURE0);

// draw the objects

glBindTexture(GL\_TEXTURE\_2D, texture2);

simple\_cube\_t->render(mt\_shader);

glBindTexture(GL\_TEXTURE\_2D, texture);

simple\_globe\_t->render(mt\_shader);

}

This is done in the cube render function. We start by calculating the object matrix. This is the product of the *translation*, *rotation* and *scale* matrix. Matrix multiplication is not commutative so we must keep this order when we calculate our object matrix. Then we pass this matrix to the shader and draw our mesh.

virtual void render(cg\_shader\* \_shader) {

if (!vao) return;

// position object

mat4 ob\_matrix = tmat \* rmat \* smat;

// pass transformation to shader

\_shader->set\_mat4("model", ob\_matrix);

glBindVertexArray(vao);

if (draw\_elements) {

// setup drawing

glFrontFace(GL\_CCW);

glPolygonMode(GL\_FRONT, draw\_mode);

glDrawElements(GL\_TRIANGLES, (unsigned int)m\_mesh\_data->indices.size(), GL\_UNSIGNED\_SHORT, 0);

}

else {

// setup drawing

glPatchParameteri(GL\_PATCH\_VERTICES, 4);

glPolygonMode(GL\_FRONT\_AND\_BACK, draw\_mode);

glDrawArrays(GL\_PATCHES, 0, (unsigned int)m\_mesh\_data->indices.size());

}

glBindVertexArray(0);

}

### Adding textures

Realistic 3D environments, especially in games, are based on illusions. Illusions generated by images. These are the textures applied on surfaces. It is a lot easier, and faster, to use the image of a complicated object, instead of drawing its geometry. Take for example the tire of a car. The tread is complex, and drawing requires a lot of graphics memory to store the geometry and GPU power to process it.

Now suppose we want to draw the earth rotating to show the change between day and night. Can you imagine the amount of data required to represent the earth's surface? If we apply a good image of the earth showing the continents and the sea on a simple sphere, we can create the illusion of the earth. We can then rotate the sphere any way we want and get a good view of the earth from any point of view we want.

We start by creating a sphere. Just like the cube, our little 3D engine has a sphere object built in. The process of creating a sphere is simple. We just call *new* to create an instance of the *cg\_gl\_sphere* class, which takes care of the *mesh* generation and all the *vertex buffers* and *vertex arrays*.

Figure : Textured sphere

The difference from the wireframe drawing we saw before is in the shaders. Instead of supplying a simple color to the rendering engine of the OpenGL it reads the texture image and feeds the renderer with the appropriate color from it.

Textures are images that we store in the GPU memory. They are used to add detail to our objects. Here we focus on images that we wrap around the objects to give them the illusion of detail.

We load an image file, only *targa* images are supported, by calling the *load\_texture* function, which returns us the texture ID on success, or -1 on failure.

Textures are like vertex buffers. We must generate them, a.k.a. allocate storage for them, and then bind them to apply any operations on them, like we do with vertex buffers.

GLuint load\_texture(const char\* fname) {

GLuint tex = -1; // default return is failure

cg\_image img; // try to load the TGA image

if (!img.load(fname))

return tex; // return failure (invalid OpenGL id)

// how bytes are aligned in memory

glPixelStorei(GL\_UNPACK\_ALIGNMENT, 1);

// enable textures for the following commands

glEnable(GL\_TEXTURE\_2D);

// we will generate a texture with mipmaps

glTexParameteri(GL\_TEXTURE\_2D, GL\_GENERATE\_MIPMAP, GL\_TRUE);

// generate texture

glGenTextures(1, &tex);

// and make it the current processing object

glBindTexture(GL\_TEXTURE\_2D, tex);

// how texture values (colors) are interpreted

glTexEnvf(GL\_TEXTURE\_ENV, GL\_TEXTURE\_ENV\_MODE, GL\_MODULATE);

// when texture area is small, bilinear filter the closest mipmap

glTexParameterf(GL\_TEXTURE\_2D, GL\_TEXTURE\_MIN\_FILTER, GL\_LINEAR\_MIPMAP\_NEAREST);

// when texture area is large, bilinear filter the original

glTexParameterf(GL\_TEXTURE\_2D, GL\_TEXTURE\_MAG\_FILTER, GL\_LINEAR);

// the texture wraps over at the edges (repeat)

glTexParameterf(GL\_TEXTURE\_2D, GL\_TEXTURE\_WRAP\_S, GL\_REPEAT);

glTexParameterf(GL\_TEXTURE\_2D, GL\_TEXTURE\_WRAP\_T, GL\_REPEAT);

// now build the mipmaps

gluBuild2DMipmaps(GL\_TEXTURE\_2D, 4,

img.get\_width(), img.get\_height(),

img.get\_image\_format(), img.get\_data\_type(), img.get\_image());

glBindTexture(GL\_TEXTURE\_2D, 0);

img.release();// release the TGA image

return tex;

}

After we setup the memory alignment, we enable the use of textures, and we declare the textures to have *mipmaps*. *Mipmaps* are precalculated images, each of which is in lower resolution than the previous.

Figure 5:mipmap image shows a *mipmap* image. This image contains copies of progressively lower resolution of the original image. Using *mipmaps* allows OpenGL to use predefined images of lower resolution when needed instead of resampling the original image every time.

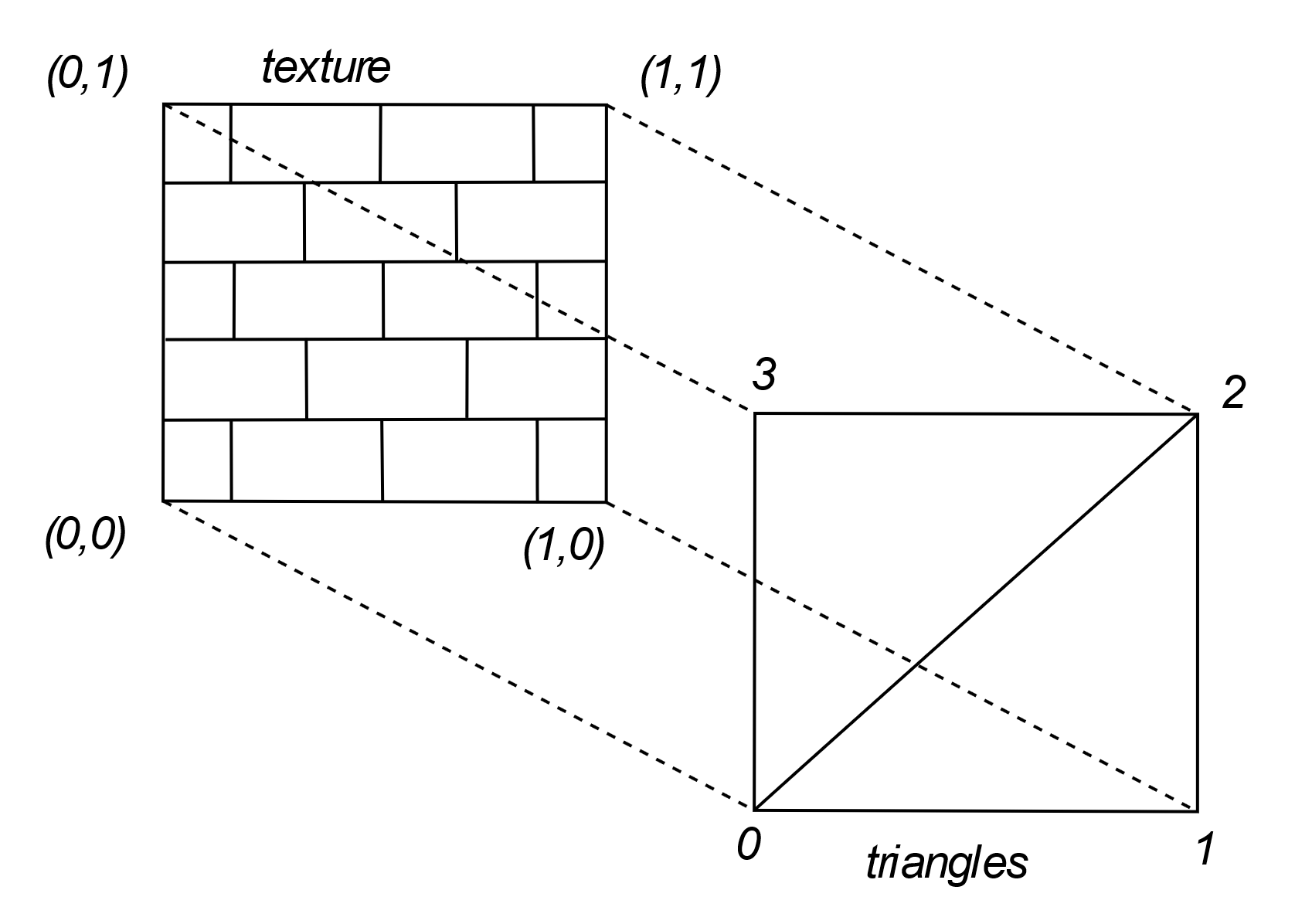
OpenGL can generate images like this when loading an image and use them when needed.

Figure :mipmap image

Then we generate and bind the texture so that all subsequent calls will act upon it. For our needs we set up our bitmaps to use the closest *mipmap* image and to repeat the texture when needed. Now that we are done parametrizing OpenGL we pass the image data and invoke the mipmap building engine.

When all is done we unbind the texture and release the image.

#### Mapping the texture

The texture was loaded into the GPU memory but how can we map the texture to the object? There must be some mapping between the image and the surface of our object. There must be some way we can tell OpenGL how to draw using colors from the image.

Here is how OpenGL addresses the problem. First the texture is given coordinates from 0 to 1 in each direction, as we see in Figure 6. Then we can assign an *s* and *t* (for *horizontal* and *vertical*) between 0 and 1, to each vertex of our mesh. A simplified mapping of an image on a simple mesh is shown in Figure 6.

When it renders the image it samples according to these coordinates to color the vertices and it interpolates for the image coordinates corresponding to the rest of the triangles surface.

Figure : Texture mapping

#### Sampling the image

The sampling of the image is done in the *fragment shader*. There we read the pixel from the image and pass it to OpenGL to finally draw. But there are some things that must be done before that.

It all starts with the *frame\_render* function, which takes care of all our drawing. First we enable the shader we have written for this purpose:

// vertex shader

#version 330 core

// vertex position in local coordinates

layout(location = 0) in vec3 aPos;

// the texture coordinates

layout(location = 2) in vec2 aTexCoord;

// texture coordinate output for fragment shader

out vec2 texCoord;

// camera has the combined viewing matrix

uniform mat4 camera;

// model has the combined matrix of object position and orientation

uniform mat4 model;

void main() {

// calculate final vertex position in the 3D space

gl\_Position = camera \* model \* vec4(aPos, 1);

texCoord = aTexCoord;

}

// fragment shader

#version 330 core

// the texture coordinate

in vec2 texCoord;

// the image we take samples from

uniform sampler2D textureSampler;

// drawing color for OpenGL to use

out vec4 color;

void main() {

color = vec4(texture(textureSampler, texCoord).rgb,1);

}

The vertex shader apart from setting the vertex coordinates has one more job to do. It reads the texture coordinates of the vertex and passes them to the fragment shader. The fragment shader then uses these coordinates to read the color data from the texture image and pass that value to OpenGL.

Now there is only one thing left to clear. Where do we find this image we sample from? This is done by binding the texture right before we call the sphere to render itself. The texture sampler accesses the last texture that was bound.

### Summary

In this part we were introduced to the ***atlas*** game engine that we are going to use from now on.

We saw how the ***atlas*** engine creates simple 3D objects like cubes and spheres.

We were introduced to some simple animation.

Finally, we brought some life to our objects using textures.

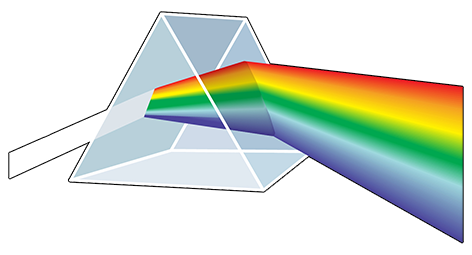
## Part 5: Lights please

The main perception of three dimensions comes from the shades. The human eye can only see colors and shades, but not the outlines. It is the transition from one color to the other that signals the change into our brain. Similarly, the change in the shadows and the difference of light and color perception between our eyes, informs our brain about the third dimension.

Color perception depends on light. The light that reaches our eyes stimulates our optical nerve. This light is emitted from various sources and reflected by the surfaces all around. The color of a surface is the combined result of the light that falls on that surface and its physical characteristics that reflect, absorb or scatter part of that light.

In this part we will try to clear up things about the light and see how we can use all that to our advantage.

### The color of things

We use special materials, usually liquid, to dye the surfaces of objects to our desired color. These liquids are called paints. No big news so far. But how do these paints work? How do they change what we see?

The color we see is the color of the light that reaches our eyes. The light of the sun is what we call the *white* light. It is the mixture of all the colors we know. Sir Isaak Newton was the first to understand it back in 1666. Many people see the same thing but only one comes to the right conclusions.

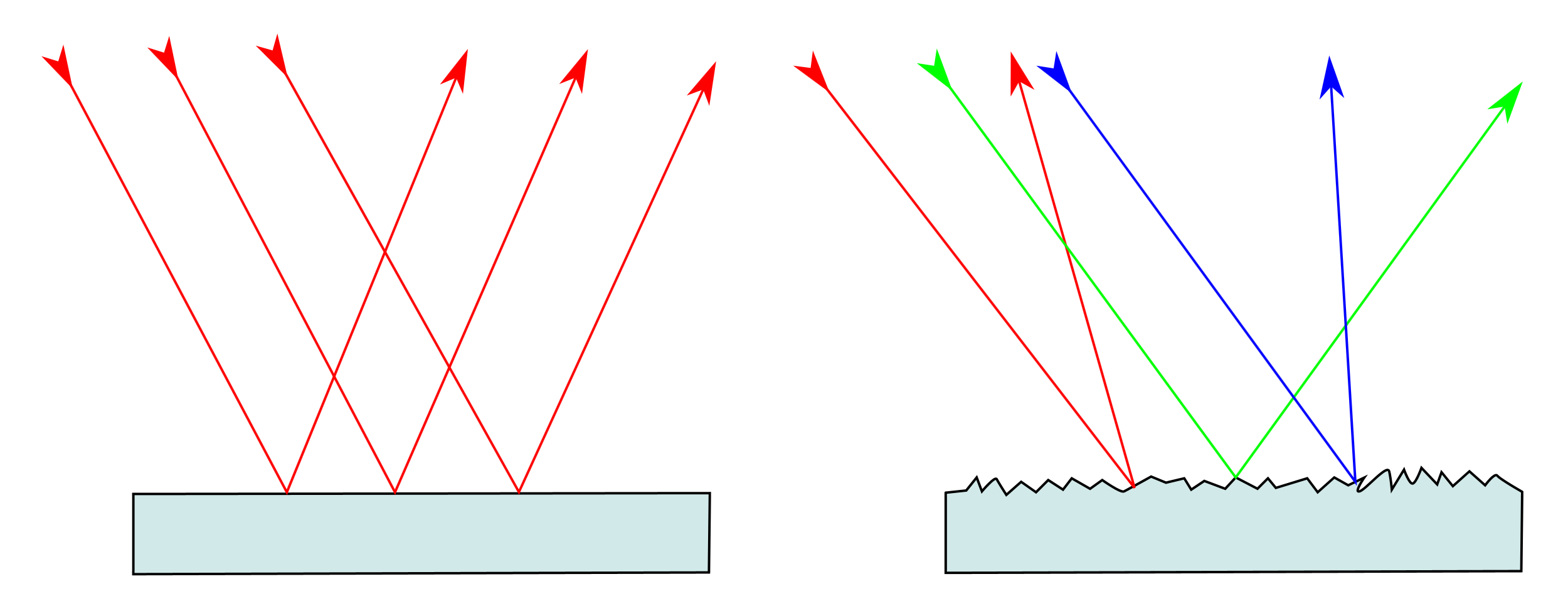
The various light sources emit anything from white light to light of a specific color or combination of colors that gives them their characteristic color. Τhe light travels in a straight line but the dust particles in the air refract it and this is a part of the *ambient* light in the scene.

Figure : Color spectrum of white light

The light emitting sources are point sources. The light emitted from them goes radially. When the source is too far, say like the sun, we consider the light to be emitted in parallel. This *direct* light makes our scene bright, and the objects shine.

The light rays that reach the surface of an object are reflected. Some of the light though is absorbed by the object and some is reflected. This results in the color we see for the object. This is the job of the paint; it absorbs all the colors but those we see.

Figure : Reflection and diffusion

Object surfaces are not as smooth as think. They are a little rough, enough to reflect the light in various directions. Figure 8 shows the ideal reflection on the left and the actual on the right. This phenomenon is called *diffusion* and scatters the light adding to the *ambient* light. Ambient light allows us to see in areas shadowed by objects.

The light that we see is the sum of the direct light that reaches our eyes, the reflected light from the surfaces of the objects in the form of *diffuse* and *specular* light, and the ambient light. The color of the objects is also a function of the color of the light that falls on them. If we drop red light on a blue surface we cannot expect to see the surface blue. It will be black if the light is pure red or some version of purple. The color of the light is described by the *diffuse* attribute of the light.

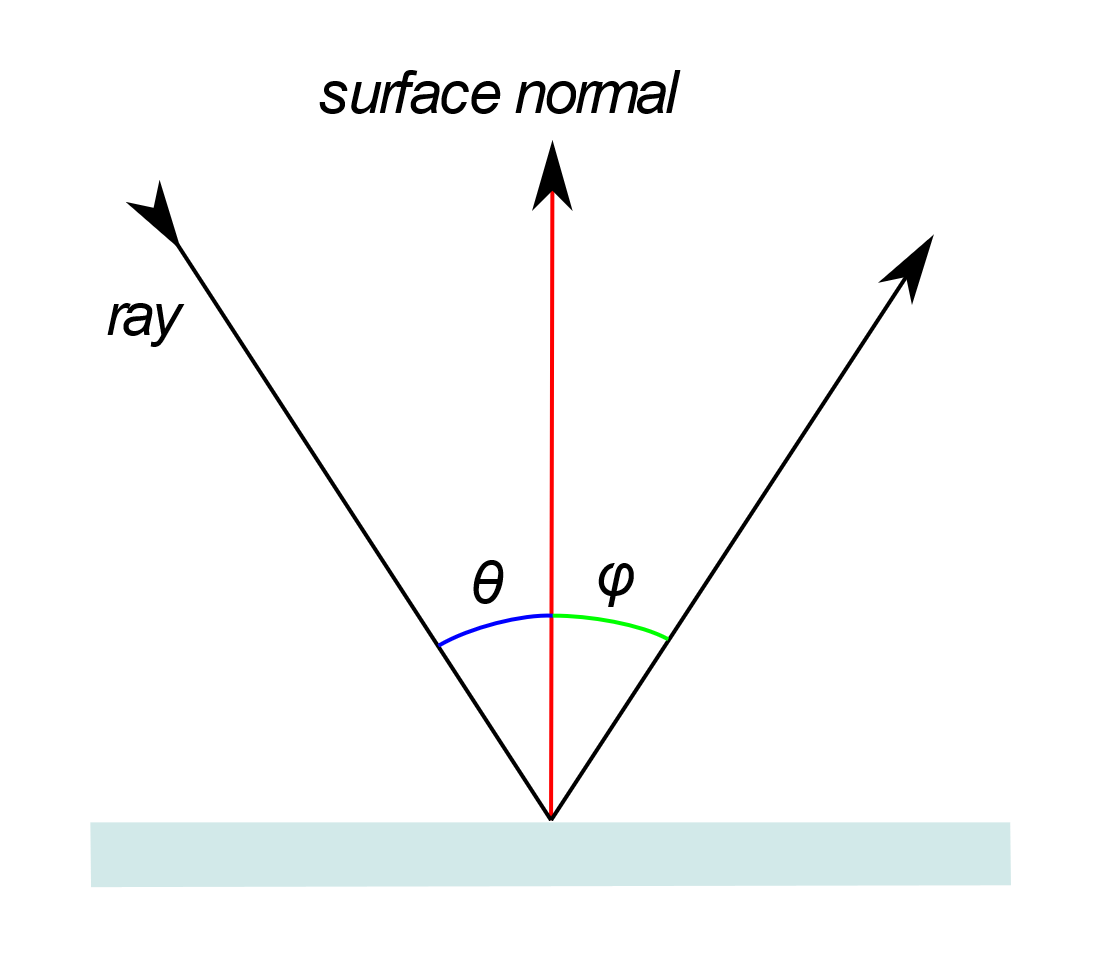
### RGB

*Red, Green, Blue*. These three are the components that define any color. Our eyes are like camera sensors, or to put it right, we modeled camera sensors after our eyes. Our eyes have light sensing cells which covert the light and the color to signals stimulating our optical nerves.

These sensors are sensitive to red, green, and blue light. The combination of these three colors makes the colors we see. Deep in the human eye there are light receptors which are sensitive to these colors. This is the actual reason we have modeled the camera sensors like this. There are more sensors in the eye, but they are responsible for other features of our perception of the world around us.

OpenGL has modeled anything that has to do with color with *red, green,* and *blue.*

### Reflections

The rays of light that are reflected off the surface are not scattered in random directions. Reflection follows certain rules. We are all familiar with these rules either by playing with a mirror in the sun or any game with a ball that hits a wall and comes back.

The **law of reflection** indicates that the ***angle of incidence*** equals the ***angle of reflection***. This might mean nothing but looking at Figure 9 it will get clear. Here we have a ray falling on a smooth surface and we mark with red the normal vector of it. ***Angle of incidence*** is the angle between the ray moving towards the surface and the normal vector and is marked as . ***Angle of reflection*** is he angle between the ray moving away from the surface and the normal vector and it is marked with . These two angles are *always equal*.

If the surface is rough we might think that this is not the case. If we take a closer look though we will see that the surface at the point of incidence is not in the direction we thought it was. Surfaces as we said are rough at microscopic level, making us think that light behaves strangely, and not according to the laws of nature.

Figure : The law of reflection

### Putting it all together

We have seen how a simple source of light behaves. It is about time to add a light source into our scene and start adding some life to it.

For our needs we have created the ***lights\_materials*** sample. In this sample we create some lighting models of increasing complexity to show some techniques we can use to add realism to our scenes.

To keep things organized and easy to use we create a class dedicated to light. This is the *cg\_light* class. It allows us to store the characteristics of the light in one place and pass them to the shader in a clean and easy way. It is implemented in the *cg\_light.h* and *cg\_light.cpp* files.

The light has three major attributes: *ambient, diffuse,* and *specular.* We will start the description from the end.

*Specular* light is the light that is directly reflected off the surface of an object to our eyes. Like the reflection of the sunlight on a mirror. The color of this light is the product of the color of the light source and the color of the object. Its intensity depends on the orientation of the object.

*Diffuse* light is generated by the roughness of object surfaces. Because of the roughness of any surface, part of the light that falls on them is reflected in random directions. Some of this randomly reflected light reaches our eyes. Its color is again a product of the *diffuse* color of the light and the color of the object.

*Ambient* light is the light that has no direct source and seems to come from all directions. It is the result of consecutive reflections of the light on various surfaces in the scene, diffusions that may occur and even diffusion caused by the atmosphere. Exact calculation of the ambient light is too complex and time consuming, so we assume that it is a constant light that is the same in all directions.

All the calculations are done in the shader. Starting with the vertex shader which, apart from calculating the vertex position in the view and extract the texture coordinates, has to calculate the position of the vertex in the 3D space as well as its *normal vector*. These two values will be needed to calculate the lighting.

Now that we have calculated the position and the normal vector of the vertex we can calculate the color of the fragment. We are starting with the easy part of our calculation, the *ambient* light. This is a simple multiplication between the *ambient* factor of the light and the light color. We do not have to calculate any direction or reflection, so we are done with one of the light components.

The other two components are the *specular* light, and the *diffused* light. These require the calculation of the light direction, the view direction, and the reflection of the light on the surface.

For the *specular* part of the light, we calculate the strength of the reflection. This determines how the reflection spreads over the surface of the object, a.k.a. how big is the bright spot on the surface. Then we combine it with the properties of the material, how shiny the object is. We will return to this later when we talk about materials, for the moment we just give it a value.

The *diffusion* determines the amount of light that comes to our eyes when the object surface is not reflecting the light to us. This is why we need the orientation calculations. We need to know if the light falls directly on it, and if so how bright it may seem to us.

The amount and the hue of the light that falls on the object is the sum of the three components we calculated. Multiplying it with the color of the object we obtain the final color we see.

This is the vertex shader we just described:

// we use the same vertex shader for all the shaders in this part

#version 330 core

// these are set in the array buffer

layout(location = 0) in vec3 aPos;

layout(location = 1) in vec3 aNormal;

layout(location = 2) in vec2 aTexCoord;

// the transformation matrices

uniform mat4 camera;

uniform mat4 model;

// data we pass to the fragment shader

out vec2 texCoord;

out vec3 Normal;

out vec3 pos;

void main() {

// some code optimization

// this product appears twice in our code

// so, we calculate it once

vec4 p = model \* vec4(aPos, 1);

// first occurrence in gl\_Position calculation

gl\_Position = camera \* p; // model\* vec4(aPos, 1);

texCoord = aTexCoord;

// vertex position in space (no view)

// second occurrence in vertex position in 3D

pos = vec3(p); // model\* vec4(aPos, 1));

Normal = mat3(transpose(inverse(model))) \* aNormal;

}

And this is the fragment shader:

#version 330 core

struct lightsource {

int type; // SPOTLIGHT=1, DIRLIGHT=2

vec3 pos\_or\_dir; // light location

vec3 ambient; // the ambience property of the light

vec3 diffuse; // the diffuse property of the light

vec3 specular; // the specular property of the light

};

uniform lightsource light;

uniform vec3 cameraPos; // viewer location

uniform vec3 objectColor; // object color

in vec3 Normal; // surface normal

in vec3 pos; // drawing position

out vec3 color; // resulting drawing color

void main() {

// ambient color

vec3 ambient = light.ambient;

// normalize is a built-in function in GLSL

// surface normal

vec3 norm = normalize(Normal);

// light direction

vec3 lightDir;

if (light.type == 1) // SPOTLIGHT

lightDir = normalize(light.pos\_or\_dir - pos);

else // DIRLIGHT

lightDir = normalize(-light.pos\_or\_dir);

// view direction

vec3 viewDir = normalize(cameraPos - pos);

// reflection vector, reflect is a built-in function in GLSL

vec3 reflectDir = reflect(-lightDir, norm);

// pow, max, dot are built in functions in GLSL

// specular strength

float spec = pow(max(dot(viewDir, reflectDir), 0.0), 128);

// specular color

vec3 specular = spec \* light.specular;

// diffusion factor (calculated by the reflection angle)

float diff = max(dot(norm, lightDir), 0.0);

// and diffusion color

vec3 diffuse = diff \* light.diffuse;

// light emitted from object is (ambient + diffuse + specular)

color = (ambient + diffuse + specular) \* objectColor;

}

### Materials

In the previous section we introduced several parameters that involved the materials of the objects and we just used arbitrary values without any explanation. In this section we are going to explain these parameters and see how they change the appearance on the objects.

So far the only parameter we had for the material of the object was the color. We all know that this is not enough. Different materials behave differently under light. Obsidian for instance is different to black rubber for a car’s tires, although they are both black.

Light and color equations are designed to consider the nature of the material and not only the color. All we must do is create another communication channel between our program and the OpenGL pipeline to pass these parameters. Then with some minor adjustments to the shader we will reach our goal.

To make all our samples comparable and clear we will use a point light source, pure white that emits light evenly to all directions. This will allow us to see and compare the effect of the materials on the result.

We use three different types of reflection to describe the light emitted from an object when the light hits it. These are *ambient*, *diffuse,* and *specular* reflections.

***Ambient*** reflection is caused by the ambient light that falls on the surface of the object. Some of this light is absorbed and some is reflected. Since there is no clear direction in the light, ambient reflection is uniform at every point on the surface. The color reflected depends on the color of the surface.

***Diffuse*** reflection is caused by the roughness of the surface. This makes the light reflect in random directions.

***Specular*** reflection is the clear reflection we get from smooth surfaces like polished metal. This gives us the shiny look of the objects. Apart from the color reflected, *specular* reflection has one more parameter, the ***shininess*** of the object.

All reflections have three components for each of the *red, green,* and *blue* components of the white light, except *shininess* which is a scalar value. In the following table you can see the values for some common materials as defined by OpenGL.

The *cg\_material* class packs all these parameters and handles the communication with the shading pipeline, writing the values in the shader program memory. The shader we created has a new structure called *material* which holds the same variables as we did before with the light.

When we have material properties we do not consider the *ambient* component of the *lightsource* structure, but we use the ambient component of the *material* instead.

The *vertex* shader is the same, but the *fragment* shader has been modified to use the properties of the material.

#version 330 core

struct lightsource {

int type; // SPOTLIGHT=1, DIRLIGHT=2

vec3 pos\_or\_dir; // light location

vec3 ambient; // the ambience property of the light

vec3 diffuse; // the ambience property of the light

vec3 specular; // the ambience property of the light

};

uniform lightsource light;

struct material {

// how the material reacts to light

vec3 ambient;

vec3 diffuse;

vec3 specular;

float shine; // surface shine

};

uniform material mat;

in vec3 Normal; // surface normal

in vec3 pos; // drawing position

uniform vec3 cameraPos; // viewer location

out vec4 color; // resulting drawing color

void main() {

// ambient color based on material properties as well

vec3 ambient = light.ambient \* mat.ambient;

// surface normal

vec3 norm = normalize(Normal);

// light direction

vec3 lightDir;

if (light.type == 1)

lightDir = normalize(light.pos\_or\_dir - pos);

else

lightDir = normalize(-light.pos\_or\_dir);

// view direction

vec3 viewDir = normalize(cameraPos - pos);

// reflection vector

vec3 reflectDir = reflect(-lightDir, norm);

// specular strength

float spec = pow(max(dot(viewDir, reflectDir), 0.0), mat.shine);

// at last, specular color

vec3 specular = (spec \* mat.specular) \* light.specular;

// diffusion factor (calculated by the reflection angle)

float diff = max(dot(norm, lightDir), 0.0);

// and diffusion color

vec3 diffuse = light.diffuse \* (diff \* mat.diffuse);

// light emitted from object is (ambient + diffuse + specular)

vec3 result = (ambient + diffuse + specular);

color = vec4(result, 1);

}

### Color maps

The previous approach assumes a solid material like a metallic object, or an evenly painted surface. We all know that this is not the case for all objects. In the previous part we learned how to apply textures and make our objects more realistic. Here we will learn how to combine textures with material properties for even better results.

#### Textures

We are starting with textures. We are going to use a texture as material surface. Color is not enough to represent the details of the surface of the object. It is not enough when we want to draw a wooden box or the earth.

In the previous part we used an image of the earth as a texture for a sphere. Here we will use a similar image on a sphere and an image of wooden planks on a box. Only this time we will treat them as material properties rather than general textures. This will let us select from different images just by selecting different materials.

OpenGL can load several images as textures and we can address them as *GL\_TEXTURE0*, *GL\_TEXTURE1* and so on. Then we can activate the one we want to use and start drawing.

When we are dealing with a simple texture as we did before all we do is activate the first texture buffer in OpenGL and bind the texture image to that, like this.

glActiveTexture(GL\_TEXTURE0);

glBindTexture(GL\_TEXTURE\_2D, texture);

This simple approach gives meaning to the *textureSampler* variable in the *fragment shader,* and we can use it to extract parts of the image and render them on the scene.

The same principles apply when we use material techniques. We see that in the fragment shader we request the color using the *texture* function, passing it the texture buffer id, in our case *GL\_TEXTURE0* etc., and the texture coordinate. Now instead of having the texture sampler as a global *uniform*, we put it in the material structure, which now has one more member the *diffuse\_map.*

Things in the fragment shader are straight forward. The color of our object is: texture (mat.diffuse\_map, texCoord).rgb, where *mat* is the variable holding the material properties.

Now we know how to use the texture and we have reorganized our fragment shader. The next step is to learn what goes before that. How to prepare and set the textures in our program.

If we use *GL\_TEXTURE0* our *sampler2D* parameter should be zero, for *GL\_TEXTURE1* it should be 1, and so on. This was the default behavior of OpenGL when we used one texture, everything was set to 0 and we used *GL\_TEXTURE0.* So, our *material* class has two new variables: *diffuse\_map* and *diffuse\_index*. *Diffuse\_map* stores the texture id if the loaded image, and the *diffuse\_index* is the active texture index. Here is the code to set the parameters:

shdr->set\_int("mat.diffuse\_map", diffuse\_index); // GL\_TEXTURE0=0...

glActiveTexture(GL\_TEXTURE0 + diffuse\_index);

glBindTexture(GL\_TEXTURE\_2D, diffuse\_map);

The fragment color derived from the texture image is used in the calculation of the *ambient* and the *diffuse* color of the object:

// ambient color

vec3 ambient = light.ambient \* texture(mat.diffuse\_map, texCoord).rgb;

// diffusion color

vec3 diffuse = light.diffuse \* diff \* texture(mat.diffuse\_map, texCoord).rgb;

#### Specular reflections

The use of textures adds to the realism of the scene, but it also raises a new problem. The light is not reflected uniformly on the surface of the object. The object may have materials that do not behave the same under the light. Take the earth for example, the water of the oceans reflects the light more than the land.

To achieve this kind of lighting we need to pass a per fragment information to the shader. This is done using the same technique as the texture map. We create an image like the texture image, only this time we are interested in the amount of shine each fragment will receive. In the case of our hypothetical example of earth, we paint the oceans white and the land black, to define maximum shine for the water and no shine for the land.

Now we add one more *sampler2D* texture to our material. This means that our material will activate and bind two texture buffers in OpenGL, one for the texture itself, and one for the specula map.

The complete code in the material class that sets both the diffuse and specular maps is like this:

if (diffuse\_index >= 0) {

shdr->set\_int("mat.diffuse\_map", diffuse\_index); // GL\_TEXTURE0=0...

glActiveTexture(GL\_TEXTURE0 + diffuse\_index);

glBindTexture(GL\_TEXTURE\_2D, diffuse\_map);

}

if (specular\_index >= 0) {

shdr->set\_int("mat.specular\_map", specular\_index); // GL\_TEXTURE0=0...

glActiveTexture(GL\_TEXTURE0 + specular\_index);

glBindTexture(GL\_TEXTURE\_2D, specular\_map);

}

As you can see the code is identical. Now in our program we set the material like this:

m\_mat5->set\_diffuse(diffuse\_texture, 0); // use GL\_TEXTURE0 for texture

m\_mat5->set\_specular(specular\_texture, 1);// use GL\_TEXTURE1 for specular

We set the texture images we loaded, and the texture buffers we want to use. The complete fragment shader is this:

#version 330 core

struct lightsource {

int type; // SPOTLIGHT=1, DIRLIGHT=2

vec3 pos\_or\_dir; // light location

vec3 ambient;

vec3 diffuse;

vec3 specular;

};

uniform lightsource light;

struct material {

// how the material reacts to light

vec3 ambient;

vec3 diffuse;

vec3 specular;

float shine; // surface shine

sampler2D diffuse\_map; // the surface texture

sampler2D specular\_map; // the specular reflection map

};

uniform material mat;

in vec2 texCoord;

in vec3 Normal; // surface normal

in vec3 pos; // drawing position

uniform vec3 cameraPos; // viewer location

out vec4 color; // resulting drawing color

void main() {

// ambient color

vec3 ambient = light.ambient \* texture(mat.diffuse\_map, texCoord).rgb;

// surface normal

vec3 norm = normalize(Normal);

// light direction

vec3 lightDir;

if (light.type == 1)

lightDir = normalize(light.pos\_or\_dir - pos);

else

lightDir = normalize(-light.pos\_or\_dir);

// diffusion factor (calculated by the reflection angle)

float diff = max(dot(norm, lightDir), 0.0);

vec3 diffuse = light.diffuse \* diff \*

texture(mat.diffuse\_map, texCoord).rgb;

// specular

vec3 viewDir = normalize(cameraPos - pos);

vec3 reflectDir = reflect(-lightDir, norm);

float spec = pow(max(dot(viewDir, reflectDir), 0.0), mat.shine);

vec3 specular = light.specular \* spec \*

texture(mat.specular\_map, texCoord).rgb;

// light emitted from object is (ambient + diffuse + specular)

vec3 result = ambient + diffuse + specular;

color = vec4(result, 1);

}

### Summary

In this part we add some realism to our scenes. Using light and textures we can really simplify our drawing, while adding to the quality of the user experience. The image plays a major role in the way perceive what we see.

* We learned the basic concepts of color and light.
* We learned about reflected and ambient light.
* How the properties of the materials change what we see
* How to use images to draw complex surfaces with varying materials

## Part 6: Advanced concepts

In this part we will be introduced to some advanced OpenGL techniques that will spice up our scenes. Apart from learning these techniques our main goal is to see how they can make our applications a little more interesting and eye-catching.

For example, how can we implement the rear-view mirror of a car, or even how can we see through a keyhole or a glass window? In the previous part we were introduced in the use of light, but light casts shadows, how do we deal with them?

### Stencil Buffers

Text

Description automatically generatedWe are starting our exploration of the special effects with *Stencil Buffers*.

In graphic arts one of the most used tools is the stencil. This tool allows us to draw a pattern by applying ink or paint. It might be one of the oldest drawing tools ever used. The most common application of a stencil in prehistoric times was the human hand on the walls of the caves, where people painted around their hands.

This idea evolved, and now we have created tools that allow us to draw from simple text to complex patterns, using the same principle. By cutting out specific shapes on a piece of paper, we can create a stencil with letters as we see in Figure 10.

Figure : Stencil

OpenGL has a similar mechanism we can use to keep our drawing inside any shape.

What we do is create a ‘canvas’, or stencil buffer in technical terms, the size of the screen. Then we ‘cut’ out the openings that allow the paint to pass and finally draw. Here is a description of how we do it.

As you may have noticed in the beginning of our drawing function we clear the screen

glClear (GL\_COLOR\_BUFFER\_BIT | GL\_DEPTH\_BUFFER\_BIT | GL\_STENCIL\_BUFFER\_BIT);

Only in this case we have added a third option, the GL\_STENCIL\_BUFFER\_BIT which clears the stencil canvas as well and initializes it to screen size. The stencil buffer is typically initialized to black. Everything we draw on it is done in white and that marks the cut outs that will enable us to do the stencil drawing of our scene.

Using stencil buffers is a four-step process as opposed to normal drawing which is a one step process. First we enable writing to the stencil buffer. Then we draw our stencil shape. Third we enable normal drawing, and finally we draw our scene.

virtual void frame\_render() {

// set the viewport to the whole window

m\_view->set\_viewport();

// GL\_STENCIL\_BUFFER\_BIT needs mask=0xFF

glStencilMask(0xff);

glClear(GL\_COLOR\_BUFFER\_BIT | GL\_DEPTH\_BUFFER\_BIT | GL\_STENCIL\_BUFFER\_BIT);

// we are using stencil

glEnable(GL\_STENCIL\_TEST);

// prepare the stencil buffer

glColorMask(GL\_FALSE, GL\_FALSE, GL\_FALSE, GL\_FALSE);

glDepthMask(GL\_FALSE);

glStencilFunc(GL\_NEVER, 1, 0xFF);

glStencilOp(GL\_REPLACE, GL\_KEEP, GL\_KEEP); // draw 1s on test fail (always)

// draw stencil pattern

m\_shader->use();

mat4 ob\_matrix;

ob\_matrix.loadIdentity(); // at the center of the screen

m\_shader->set\_mat4("model", ob\_matrix);

m\_shader->set\_mat4("camera", ob\_matrix);

// move the window

m\_shader->set\_vec3("displacement", vec3(xcen, ycen, 0));

// disabling these to speed up drawing

glDisable(GL\_CULL\_FACE);

glDisable(GL\_DEPTH\_TEST);

pstencil->render(NULL);

// return to normal drawing

glColorMask(GL\_TRUE, GL\_TRUE, GL\_TRUE, GL\_TRUE);

glDepthMask(GL\_TRUE);

glStencilMask(0x00); // do NOT draw on black

// draw only where stencil's value is 1

glStencilFunc(GL\_EQUAL, 1, 0xFF);

// enable them before we start normal drawing

glEnable(GL\_CULL\_FACE);

glEnable(GL\_DEPTH\_TEST);

// stop moving around

m\_shader->set\_vec3("displacement", vec3(0, 0, 0));

// and proceed with normal drawing

mat4 cam\_matrix = m\_cam->perspective() \* m\_view->perspective();

m\_light->apply(m\_shader);

m\_shader->set\_mat4("camera", cam\_matrix);

m\_shader->set\_vec3("cameraPos", m\_cam->vLocation);

// draw a rectangle behind the cube to act as background

// this will make the stencil shape visible

m\_shader->set\_vec3("objectColor", vec3(0.75f, 0.85f, 0.85f));

pbackgound->render(m\_shader);

// and now draw the cube

m\_shader->set\_vec3("objectColor", vec3(.1f, .2f, .9f));

m\_cube->render(m\_shader);

// stop using stencil

glDisable(GL\_STENCIL\_TEST);

glUseProgram(0);

}

### Blending

With *blending* in OpenGL, we mean the mixing of colors when we see our scene through a semitransparent medium. This is the case when we see the world through our sunglasses, for example.

Applying glass color is quite common in virtual reality simulation and everyday practice in games.

The technique is quite simple, and the results are sometimes spectacular. So let us start demystifying it.

We will start with the object’s material. We will not use the materials from the previous part but only the object’s color, to keep things simple and focus only on what is important.

The color of the object can have a fourth component, apart from the *red, green,* and *blue,* we used so far. This is usually referred to as *alpha* channel or *transparency*. An opaque material has the value of 1 and a fully transparent has the value 0. Common objects have values anywhere between these limits.

Drawing with blending is simple but it requires some work on our side. It must be done in a specific order to achieve the desired and correct results.

First we upgrade our color to have four components adding the opacity in the alpha channel. So, our color variable for the objects’ colors are now of type *vec4* instead of *vec3.* Then we start drawing all our opaque objects. In our sample this is a spinning cube.

When we are done with the opaque objects, we draw our transparent objects. This is the process we will analyze more because here is where all the magic happens.

Our transparent objects must be ordered starting from the farthest and finishing to the closest to the viewer, and then be drawn in that order. All color calculations required for blending are performed as we pass the objects to the pipeline, and drawing order really makes a difference.

We can use texture images as textures for our transparent objects. This is a lot more flexible than using a color value for the entire surface. We can add a byte per pixel in the target image, as the alpha channel, and encode in it 256 different levels of opacity. This can give our object varying opacity over its area. We see this in our example as the blue ’glass’ changes from completely opaque to completely transparent. It is combined with a red uniform glass to show how two transparent objects can be combined.

m\_shader->use();

m\_light->apply(m\_shader);

// set the texture we will use

glActiveTexture(GL\_TEXTURE0);

glBindTexture(GL\_TEXTURE\_2D, texture);

mat4 cam\_matrix = m\_cam->perspective() \* m\_view->perspective();

m\_shader->set\_mat4("camera", cam\_matrix);

m\_shader->set\_vec3("cameraPos", m\_cam->vLocation);

// draw opaque objects first

m\_shader->set\_vec4("objectColor", vec4(0, 1, 0, 1));

// use object color parameter, do not look for texture

m\_shader->set\_int("useColor", 1);

m\_cube->render(m\_shader);

// start blending

glEnable(GL\_BLEND);

glBlendFunc(modes[source\_mode], modes[dest\_mode]);

// and now transparent objects (sorted)

if (draw\_order == 0) { // the blue glass goes back

// ignore object color and use texture

m\_shader->set\_int("useColor", 0);

pglass->move\_to(vec3(0, 0, -1.5f));

pglass->render(m\_shader);

m\_shader->set\_vec4("objectColor", vec4(.9f, .1f, .1f, 0.5f));

m\_shader->set\_int("useColor", 1);

pglass->move\_to(vec3(0, 0, 0));

pglass->render(m\_shader);

}

else { // the red glass goes back

m\_shader->set\_vec4("objectColor", vec4(.9f, .1f, .1f, 0.5f));

m\_shader->set\_int("useColor", 1);

pglass->move\_to(vec3(0, 0, -1.5f));

pglass->render(m\_shader);

m\_shader->set\_int("useColor", 0);

pglass->move\_to(vec3(0, 0, 0));

pglass->render(m\_shader);

}

glBindTexture(GL\_TEXTURE\_2D, 0);

// stop blending

glDisable(GL\_BLEND);

As we said before the color of the incoming fragment is combined with the color of the corresponding fragment in the frame buffer.

The following equation is applied.

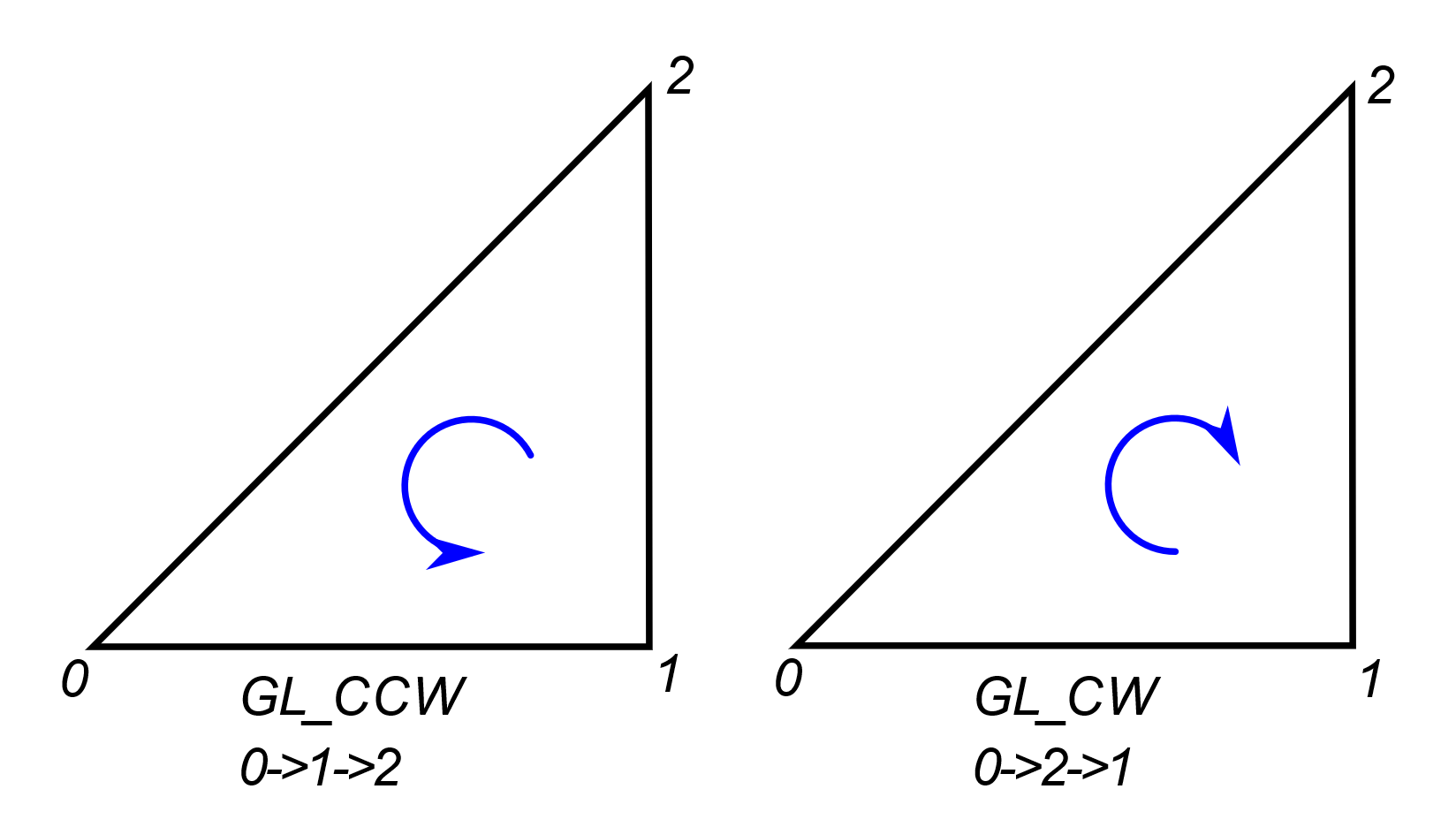
Where *source* is the output of the fragment shader, and *dest* is the content of the frame buffer. The *Factor* is calculated according to the parameters given to the *glBlendFunc*.

|  |  |
| --- | --- |
| Option | Factor is equal to |
| GL\_ZERO | 0 |
| GL\_ONE | 1 |
| GL\_SRC\_COLOR |  |
| GL\_ONE\_MINUS\_SRC\_COLOR |  |
| GL\_DST\_COLOR |  |
| GL\_ONE\_MINUS\_DST\_COLOR |  |
| GL\_SRC\_ALPHA |  |
| GL\_ONE\_MINUS\_SRC\_ALPHA |  |
| GL\_DST\_ALPHA |  |
| GL\_ONE\_MINUS\_DST\_ALPHA |  |

You can experiment with the blending options and see how OpenGL handles it. Blending in OpenGL is not difficult. There is only one thing to remember. Never break the order of execution:

* Render opaque objects.
* Render transparent objects sorted according to their distance from the viewer.

### Face culling

The number of faces in 3D applications increases as the available computation power increases. The situation is getting worse as the complexity of the scene increases. The system has to perform all those tasks required raising the barrier even higher. If OpenGL could easily identify which faces are actually facing away from the screen it could completely ignore them while drawing and speed the rest of the drawing process dramatically.

We know that a great part of the surface of a solid object is invisible to us. The part that faces away from us, the back of the object as we call it. The viewer never sees those faces, and they usually measure more than 50% of the total number of faces we must draw in our scene. Imagine the amount of work required to calculate how to draw things that will finally be rejected because they are behind other objects.

Figure : Clock and Counterclockwise definition of a triangle

There is an easy way to define if a face is pointing towards the viewer. We will use a simple triangle to illustrate the method. As you can see in Figure 11, we can define the triangle issuing its vertices in a counter clock or clockwise manner. If we define all our triangles consistently, then the triangles in the back facing surfaces will be drawn the opposite way due to the space transformation. This is a clear sign that we can skip them.

We can ‘tell’ OpenGL which rotation is front facing and which is back facing, as well as which is to be omitted from drawing. I prefer to define counterclockwise as the positive rotation because it follows the right-hand rule which I find helpful when setting up the calculations for my game. The basic rule is to be consistent, and you can follow any rule you feel more comfortable with.

To achieve back face culling is easy. We start by enabling the feature in OpenGL.

glEnable(GL\_CULL\_FACE);

Then we define which rotation faces front, and which we want to draw, front facing, back facing or both.

glFrontFace(GL\_CCW);

glPolygonMode(GL\_FRONT, draw\_mode);

The benefit of using this technique in small programs like the samples of this book is negligible. As the points and faces count increases though it makes a huge difference.

### Cubemap / Skybox

Cubemaps simplify the texture we can apply on a cube, hence the name cubemap. It is an easy way to draw the distant horizon, the sky above and the earth below.

Imagine yourself being in a huge cubic box, the faces of which display carefully selected images of the surrounding environment, creating a panorama of whatever is around us.

These are the steps we need to follow to create a cubemap. The first step is to generate a texture, just like any other texture by calling the glGenTextures function. Then we must activate this texture by binding it with glBindTexture. Here is the first difference from ordinary textures. Instead of using the GL\_TEXTURE\_2D parameter, we use the GL\_TEXTURE\_CUBE\_MAP. This is used in all the texture functions we use for the cubemap.

The next step is to load the images. Loading the images has no new feature to talk about. After loading the images, we store them in OpenGL using glTexImage2D. The first parameter of this function is one of the cube face ids. Let me explain this in more detail.

The first value defined in OpenGL is GL\_TEXTURE\_CUBE\_MAP\_POSITIVE\_X. This means that the corresponding image will be used for the face lying on the YZ plane and has positive X coordinate. The five other values are GL\_TEXTURE\_CUBE\_MAP\_NEGATIVE\_X, GL\_TEXTURE\_CUBE\_MAP\_POSITIVE\_Y, GL\_TEXTURE\_CUBE\_MAP\_NEGATIVE\_Y, GL\_TEXTURE\_CUBE\_MAP\_POSITIVE\_Z, GL\_TEXTURE\_CUBE\_MAP\_NEGATIVE\_Z, mapping the other five faces.

At the end we have created a texture with six layers, as referred to in OpenGL documentation. Each layer has an ID based on its location and is assigned a texture image.

The coordinate system for cubemaps used internally by OpenGL is left-handed. So positive X points to the RIGHT, positive Y points UP, and positive Z points to the from the viewer to the screen. On the other hand, our game engine uses a right-handed coordinate system. This combination creates a problem when displaying cubemaps. The textures are rotated by and left and right are swapped. To fix this we rotate the images after we have loaded them, and we swap the left and right images.

Here is the code that loads the texture images for the cubemap.

glGenTextures(1, &textureID);

glBindTexture(GL\_TEXTURE\_CUBE\_MAP, textureID);

for (auto i = 0; i < 6; i++) {

cg\_image\* img = new cg\_image;

img->load(faces[i].c\_str());

// the coordinate system for cubemaps is left-handed

// and the coordinate system of our engine is right-handed

// so, we rotate the images by 180 degrees

img->rotate180();

glTexImage2D(GL\_TEXTURE\_CUBE\_MAP\_POSITIVE\_X + i, 0, img->format(),

img->width(), img->height(), 0, img->format(),

GL\_UNSIGNED\_BYTE, img->image());

delete img;

}

The naming and coordinate convention we need to follow when we use the underlying engine to draw a skybox is as follows.

|  |  |
| --- | --- |
| Coordinate macro | Relative position |
| GL\_TEXTURE\_CUBE\_MAP\_POSITIVE\_X | Right |
| GL\_TEXTURE\_CUBE\_MAP\_NEGATIVE\_X | Left |
| GL\_TEXTURE\_CUBE\_MAP\_POSITIVE\_Y | Up |
| GL\_TEXTURE\_CUBE\_MAP\_NEGATIVE\_Y | Down |
| GL\_TEXTURE\_CUBE\_MAP\_POSITIVE\_Z | Front |
| GL\_TEXTURE\_CUBE\_MAP\_NEGATIVE\_Z | Back |

Our cubemap texture is now ready. The next thing we are going to analyze is the drawing of the skybox. We expect drawing to be easy, after all this is the reason we use this technique.

And it is easy to use the skybox. To begin with all we need is the vertex coordinates. No texture mapping coordinates or vertex normal are required. Since our object is a simple cube and the texture maps directly to the vertices of each face, OpenGL can easily choose the correct image and mapping based on the vertex coordinates alone.

The other thing we need is the location and orientation of the camera, the point in space we are looking to, and the angle of our field of view. In other words, the *view* and *camera* matrices. We should note here that we removed the positioning part from the camera matrix. This is done because we are placing our viewer in the center of the cube, which is supposed to be big.

The viewer matrix defines the view vector which is used by OpenGL to determine the fragment of the texture to render. It will automatically select the image or layer to use and apply all the necessary transformations. The shader code is in the *cg\_skybox.cpp* file for easier installation of the engine and the samples.

// the skybox vertex shader

#version 330 core

layout(location = 0) in vec3 aPos;

uniform mat4 view;

out vec3 texCoords;

void main() {

// vertex coordinates are used for texture coordinates

texCoords = aPos;

vec4 pos = view \* vec4(aPos, 1.0);

gl\_Position = pos.xyww;

}

// the skybox fragment shader

#version 330 core

in vec3 texCoords;

uniform samplerCube cg\_skybox;

out vec4 color;

void main() {

color = texture(cg\_skybox, texCoords);

}

### Environment mapping

We can dramatically improve our drawing and make it more realistic if we calculate the reflections of the environment onto the surfaces of our objects. The technique is called *raytracing,* and it is a simulation of whatever happens in nature.

Unfortunately, this is a very computationally intensive technique, and complex scenes take too long to render. Even with state-of-the-art hardware, the rendering speed is not good for gaming or any other real-time application.

One technique to help us achieve equally great results is *Environment mapping.* In this we create reflections of texture images on the surfaces we want. This is very efficient since all the light effects are precalculated and encoded in the texture image.

This technique complements the skybox we saw before. Instead of rendering the images on the surrounding cube, we render their reflections on the objects in the scene. The reflections can be rendered even if we do not draw the skybox.

We just set up the texture as we do in the skybox and then with the help of our shaders we calculate the reflections on the objects. In the sample code (cubemap.cpp) you can comment out the rendering of the skybox and still see it rendered on the objects.

To use *environment mapping* we create a skybox and use its texture. The skybox class contains all the code required to load the texture images and then use them to generate OpenGL textures.

All the work is done in the shader and more precisely in the *fragment shader*. In the *vertex shader* we perform the usual calculations we did in when we had to apply light and texture:

// vertex shader

#version 330 core

layout(location = 0) in vec3 aPos;

layout(location = 1) in vec3 aNormal;

layout(location = 2) in vec2 aTexCoord;

uniform mat4 camera;

uniform mat4 model;

out vec3 Normal;

out vec3 pos;

out vec2 texCoord;

// nothing unusual in the vertex shader

void main() {

gl\_Position = camera \* model \* vec4(aPos, 1);

pos = vec3(model \* vec4(aPos, 1));

Normal = mat3(transpose(inverse(model))) \* aNormal;

texCoord = aTexCoord;

}

In the *fragment shader* on the other hand, we calculate the vector from the camera position to fragment position and calculate its reflection on the surface with the help of the normal vector. The reflected vector points to the location on the *skybox* and that is where we get the color to render.

// fragment shader

#version 330 core

uniform int useColor; // use color=1 or texture=0

uniform vec4 objectColor; // object color to use

uniform vec3 cameraPos; // viewer location

uniform samplerCube skybox; // skybox texture

in vec3 Normal; // surface normal

in vec3 pos; // drawing position

out vec4 color; // resulting drawing color

void main() {

// used when drawing text

if (useColor == 1) {

color = objectColor;

}

// used for textured objects

else {

// calculate reflection and not direct view

vec3 view = normalize(pos - cameraPos);

// reflect is a built-in function in GLSL

vec3 reflection = reflect(view, normalize(Normal));

// the reflection vector determines the output color

color = vec4(texture(skybox, reflection).rgb, 1.0);

}

}

The reflection is calculated by the *reflect* function which is a built-in function in GLSL. It takes two arguments, the vector to be reflected and the normal vector of the surface at the reflection point.

### Frame buffers

According to the official definition, a *Frame buffer* in OpenGL is a buffer that can be used as the destination for rendering. There are two types of frame buffers. First is the default frame buffer, which we have used so far for rendering, and the user-created frame buffer which is usually called Frame Buffer Object of FBO for short.

You may wonder why we need frame buffers and what we can do with them. Well, consider the following situation. Somewhere in your game scene there is a television which is on, playing some animation. Using a frame buffer can help you create that effect. You can render the animation using a frame buffer and then use that buffer as a texture for the television screen when rendering the main scene.

As is the case with all the OpenGL tools we have seen so far, a frame buffer must be created before we can start using it. You can view the frame buffer as a painter’s canvas on which we can draw and then hang it on our wall as a piece of art that decorates our scene.

Here is the code that creates the frame buffer.

unsigned int cg\_texture\_buffer::create(int w, int h) {

glGenFramebuffers(1, &m\_buffer);

glBindFramebuffer(GL\_FRAMEBUFFER, m\_buffer);

// create a color attachment texture

glGenTextures(1, &m\_texture);

glBindTexture(GL\_TEXTURE\_2D, m\_texture);

glTexImage2D(GL\_TEXTURE\_2D, 0, GL\_RGB, w, h, 0,

GL\_RGB, GL\_UNSIGNED\_BYTE, NULL);

glTexParameteri(GL\_TEXTURE\_2D, GL\_TEXTURE\_MIN\_FILTER, GL\_LINEAR);

glTexParameteri(GL\_TEXTURE\_2D, GL\_TEXTURE\_MAG\_FILTER, GL\_LINEAR);

glFramebufferTexture2D(GL\_FRAMEBUFFER, GL\_COLOR\_ATTACHMENT0,GL\_TEXTURE\_2D, m\_texture,0);

glBindFramebuffer(GL\_FRAMEBUFFER, 0);

return m\_buffer;

}

You will notice the great resemblance between this and the creation of other objects we have seen so far. In this case we create a frame buffer and then we create a texture which we attach to the frame buffer. Something like setting a frame and a canvas.

After its creation we can leave the frame buffer until we need to draw on it. When that time comes we must call the glBindFramebuffer function passing the buffer ID like this:

glBindFramebuffer(GL\_FRAMEBUFFER, m\_buffer);

From that point on all our drawing is redirected to the frame buffer. To stop the redirection, we call the same function with a value of 0 as a frame buffer ID. Now the frame buffer contains an image that can be used for anything we want. The most common use is as a texture image somewhere in our program.

The texture object inside the frame buffer class is just like any other image texture we have used so far. All we must do is bind and use it in our drawing.

In the example *frame\_buffers* I use two different shaders, one while rendering in the frame buffer and one while rendering the actual scene. A close look at the shader code will make clear that the only reason for this is to demonstrate that they can be two completely different scenes.

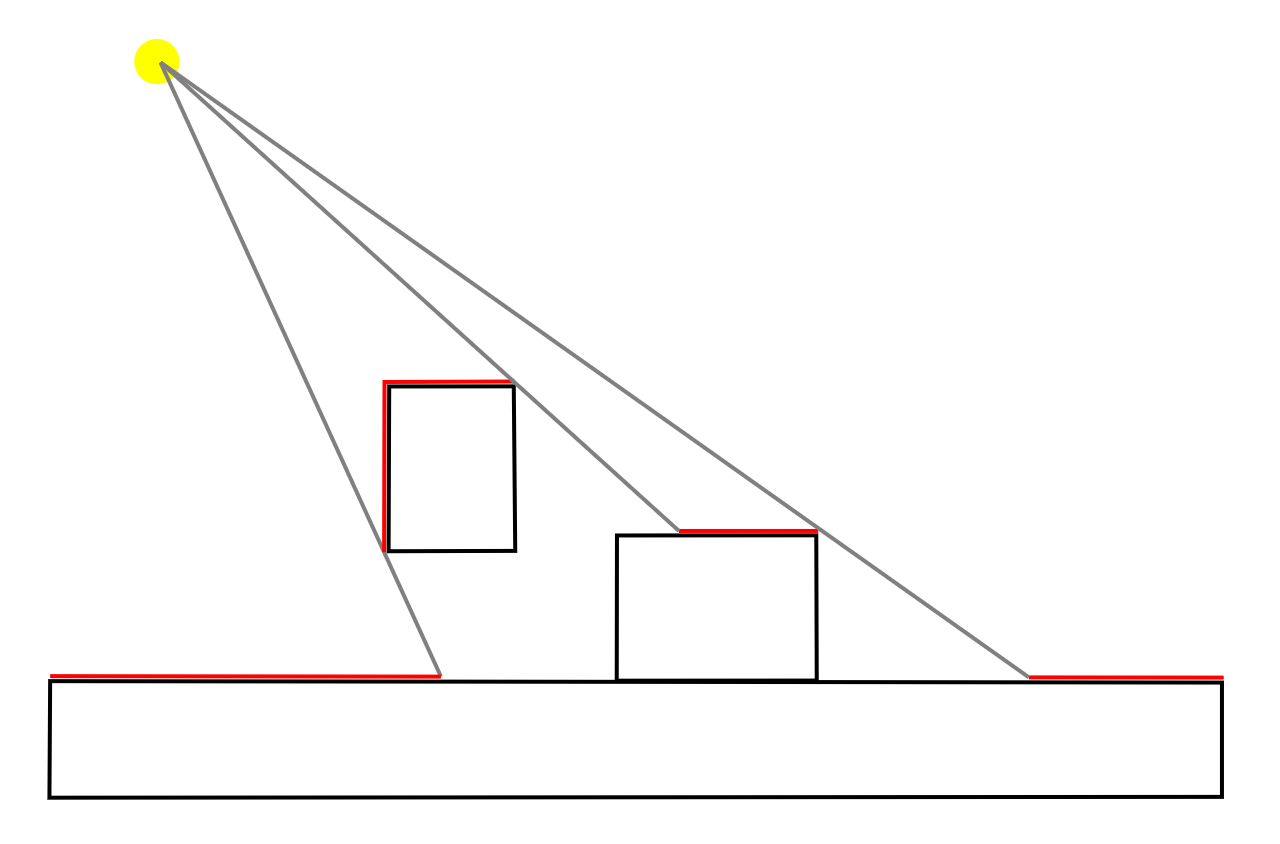
In the first part of the rendering function, we draw in the frame buffer a rotating cube. Then in the second part we use that image as a texture for a rotating sphere.

### Shadows

We are all familiar with shadows in our everyday life. So far we have learned how to deal with light in our games. We have learned how it reflects on the surfaces of objects and creates all the nice effects. However, our scenes seem empty. Our brain expects the light to cast shadows and when we do not see them we get that strange feeling.

According to the dictionary shadow is *the dark figure cast upon a surface by a body intercepting the rays from a source of light*. This definition really shows us what to do to get some realistic renderings with shadows.

The best way to calculate shadows is the technique called *raytracing*. In this method we trace the rays of light and simulate the effect they have when they hit an object. This way we can generate all the shininess and reflection we have seen so far. This automatically generates shadows since the areas the light cannot reach remain unlit.

Raytracing is the method of choice for high quality rendering and modern graphic cards provide specialized hardware to assist calculations. However, it is still far from becoming the mainstream technique for games. You see ray-tracing algorithms are very computationally intensive and the time needed for a scene to render is too long compared to the time available in our applications. Here we should add the very expensive hardware needed for these cutting-edge technologies.

To overcome these problems and still have realistic scenes other techniques have been proposed and are used by game developers. The technique used by the most video games is *shadow mapping*. This is an easy to understand and implement technique, as well as fast with great results. All these make it an excellent choice for video games.

We will start by explaining the idea behind shadow mapping. First look at Figure 12. The areas marked in red are in the way of light and their color can be calculated as we have seen before. The rest of the surfaces are not lit directly because the light is obscured.

Figure : Objects in the shadow

A closer look at this image reveals the actual algorithm on which shadow mapping is based.

In this algorithm we create an image from the light point of view. We imagine our camera is in the position of the light source and it is looking to the direction the light points.

This approach reveals the fragments of the scene that receive direct light. Here comes the real trick. In the frame buffer we store the distance of the fragment from the light source, or our imaginary camera. Every other fragment in that direction is in the shadow.

In the next step we render our scene as normal based on our camera. Before deciding the final color of a fragment, we calculate its distance from the light source and compare it with the distance stored in the shadow buffer. If the distance calculated is greater than the distance stored then the fragment is in the shadow and should be treated appropriately.

The approach presented here is a simple one and the light is treated as directional light. This means that we treat all light rays as parallel as the light rays from a very distant light source like the sun and not as rays from a small source nearby where the rays are radial.

The added complexity required for accurate shadow calculations for point light and especially when there is more than one light source belongs in an OpenGL focused book.

Now let us see the details of shadow mapping. As we said first we render our scene in an off-screen buffer. OpenGL provides the type of buffer we need for this purpose. We created a GL\_FRAMEBUFFER like we used in the previous section. This time the texture we attach to it has the GL\_DEPTH\_ATTACHMENT attribute. This instructs OpenGL that we will store distances and not colors. Our game engine has a class called *cg\_depth\_buffer* which takes care of the trivial tasks. For our needs, a 1024x1024 pixel buffer is enough. Here is how we create the buffer:

unsigned int cg\_depth\_buffer::create(int w, int h) {

// configure depth map FBO

glGenFramebuffers(1, &m\_buffer);

glBindFramebuffer(GL\_FRAMEBUFFER, m\_buffer);

// create depth texture

glGenTextures(1, &m\_texture);

glBindTexture(GL\_TEXTURE\_2D, m\_texture);

glTexImage2D(GL\_TEXTURE\_2D, 0, GL\_DEPTH\_COMPONENT, w, h, 0,

GL\_DEPTH\_COMPONENT, GL\_FLOAT, NULL);

glTexParameteri(GL\_TEXTURE\_2D, GL\_TEXTURE\_MAG\_FILTER, GL\_NEAREST);

glTexParameteri(GL\_TEXTURE\_2D, GL\_TEXTURE\_MIN\_FILTER, GL\_NEAREST);

glTexParameteri(GL\_TEXTURE\_2D, GL\_TEXTURE\_WRAP\_S, GL\_CLAMP\_TO\_EDGE);

glTexParameteri(GL\_TEXTURE\_2D, GL\_TEXTURE\_WRAP\_T, GL\_CLAMP\_TO\_EDGE);

// attach depth texture as FBO's depth buffer

glFramebufferTexture2D(GL\_FRAMEBUFFER, GL\_DEPTH\_ATTACHMENT, GL\_TEXTURE\_2D,

m\_texture, 0);

glDrawBuffer(GL\_NONE);

glReadBuffer(GL\_NONE);

if (glCheckFramebufferStatus(GL\_FRAMEBUFFER) != GL\_FRAMEBUFFER\_COMPLETE)

m\_buffer = 0;

glBindFramebuffer(GL\_FRAMEBUFFER, 0);

return m\_buffer;

}

The 2D texture attribute we use means that this image will be used as a “texture” at the second stage of our rendering operation. Our rendering function looks like this:

virtual void frame\_render() {

// create the depth buffer from the light point of view

mat4 l\_projection(ortho(-10, 10, -10, 10, 0.1f, 70.f));

mat4 l\_view(lookAt(m\_light->get\_position(),vec3(0.0f),vec3(0.0,1.0,0.0)));

mat4 lightSpaceMatrix(l\_projection \* l\_view);

// render scene from light's point of view

depth\_shader->use();

// the projection matrix in light space

depth\_shader->set\_mat4("lightSpaceMatrix", lightSpaceMatrix);

glViewport(0, 0, 1024, 1024);

d\_buffer->bind();

glClear(GL\_DEPTH\_BUFFER\_BIT);

glCullFace(GL\_FRONT);

// render our scene

render\_scene(depth\_shader);

glCullFace(GL\_BACK);

d\_buffer->release();

// --------------------------------------------------------

// set the viewport to the whole window

m\_view->set\_viewport();

glClearColor(0.2f, 0.2f, 0.2f, 1);

glClear(GL\_COLOR\_BUFFER\_BIT | GL\_DEPTH\_BUFFER\_BIT);

m\_shader->use();

m\_light->apply(m\_shader);

mat4 projection = m\_view->perspective();

mat4 view = m\_cam->perspective();

m\_shader->set\_mat4("projection", projection);

m\_shader->set\_mat4("view", view);

// the projection matrix in light space

m\_shader->set\_mat4("lightSpaceMatrix", lightSpaceMatrix);

glActiveTexture(GL\_TEXTURE0);

glBindTexture(GL\_TEXTURE\_2D, d\_buffer->texture());

m\_shader->set\_int("shadowMap", 0);

// render our scene

render\_scene(m\_shader);

// the following will be analyzed in the next part

m\_shader->set\_vec4("objectColor", vec4(.9f, .1f, .1f, 0.5f));

font2D->set\_position(5, 5);

font2D->render(m\_shader, "press Esc to exit");

glUseProgram(0);

}

The first part of the function renders the scene from the light point of view like rendering on the screen. Then in the second part we bind the texture we created and render our scene from the player’s point of view.

Now we are going to look at the shader code used. We start with the shader we use for the depth buffer. Here we only need the position of the point which is calculated in the vertex shader and stored in the *gl\_Position* predefined variable. The fragment shader can be empty or omitted completely.

#version 330 core

layout(location = 0) in vec3 aPos;

uniform mat4 lightSpaceMatrix;

uniform mat4 model;

void main() {

gl\_Position = lightSpaceMatrix \* model \* vec4(aPos, 1.0);

}

This builds our depth buffer, and we proceed to our normal rendering where all the magic happens. The vertex shader calculates the final position if the vertex and stores it in *gl\_Position* as usual, but it also calculates the vertex position in the light space as did the depth vertex shader. This light space position will be used to check if the final fragment is in the shadow.

The fragment shader introduces a new function we call *shadow\_calculation* which reads the depth buffer to determine whether the fragment is in the shadow or not.

#version 330 core

in vec3 pos;

in vec3 Normal;

in vec2 TexCoords;

in vec4 posLightSpace;

struct lightsource {

int type;

vec3 pos\_or\_dir;

vec3 ambient;

vec3 diffuse;

vec3 specular;

};

uniform lightsource light;

uniform sampler2D shadowMap;

uniform vec3 cameraPos;

uniform vec3 objectColor; // object color

out vec4 color;

float shadow\_calculation() {

// perform perspective divide

vec3 projCoords = posLightSpace.xyz / posLightSpace.w;

// transform to [0,1] range

projCoords = projCoords \* 0.5 + 0.499;

// get closest depth value from light's perspective

// (using [0,1] range fragPosLight as coords)

float closestDepth = texture(shadowMap, projCoords.xy).r;

// get depth of current fragment from light's perspective

float currentDepth = projCoords.z;

// check whether current frag pos is in shadow

float shadow = currentDepth > closestDepth ? 1.0 : 0.0;

return shadow;

}

void main() {

vec3 normal = normalize(Normal);

vec3 ambient = light.ambient;

vec3 lightDir = normalize(light.pos\_or\_dir);// -pos);

float diff = max(dot(lightDir, normal), 0.0);

vec3 diffuse = diff \* light.diffuse;

vec3 viewDir = normalize(cameraPos - pos);

vec3 reflectDir = reflect(-light.pos\_or\_dir, normal);

vec3 halfwayDir = normalize(light.pos\_or\_dir + viewDir);

float spec = pow(max(dot(normal, halfwayDir), 0.0), 128.0);

vec3 specular = spec \* light.specular;

float shadow = shadow\_calculation();

vec3 result = (ambient + (1.0 - shadow)\*(diffuse + specular))\*objectColor;

color = vec4(result, 1);

}

You may have noticed that during the creation of the shadow map we called the *glCullFace* function and inverted which is the face to render. We used this trick to overcome an artifact called *shadow acne*. This is because the shadow map is made up of samples and the actual surface is continuous. This leads to spots where the shadow function fails, and we end up with black stripes. This trick makes the shadow map more continuous and eliminates the problem.

### Fog

Another interesting visual effect that adds a lot of reality and mystery in a game scene is *fog*. Objects that are far away generally appear less sharp and clear compared to objects that are close by.

Fog involves adjusting the color of a pixel based on its distance from the camera.

It can also enhance the depth perception.

The general implementation is as follows:

* Define the clear color to be your fog color.
* Pass a distance value to the fragment shader in some manner.
* Define fog parameters:
* Minimum distance.
* Maximum distance.
* Fog color – identical to the clear color.
* Fog relationship, e.g., linear or exponential.
* Calculate the fog factor from depth distance (in eye coordinates).
* Ensure the fog factor ranges from 0 (no fog) to 1 (maximum fog):
* The `clamp()` function is useful for this.
* Mix the lit, shaded color with the fog color:
* The `mix()` function is useful for this.

All these calculations are performed in the fragment shader. The fog class passes all the required parameters to the shader in the ‘apply’ member function.

### Heightmap

A heightmap enables the creation of intricate landscapes derived from images, often utilizing the same images applied as textures for those landscapes.

#### How is the information encoded

Images typically consist of three integer values ranging from 0 to 255 for each pixel. These values represent the primary colors—RED, GREEN, and BLUE—allowing for the 16 million colors we commonly see in images.

Now, imagine we have an aerial photograph of a location. It could be useful to encode the 'altitude' or 'elevation' of each point in the image. This is done by adding an additional value for each pixel, known as an extra channel—often referred to as the alpha channel. This new value is another integer between 0 and 255, where 0 represents the lowest altitude and 255 represents the highest altitude.

#### From image to geometry

When converting image data into geometry data, three key parameters are required. The first is the altitude variation, which determines the height of each pixel by multiplying it with the alpha channel value. The second is the length scale, representing the assumed physical distance between pixels. Since our geometry is grounded in 'real' measurements, this parameter facilitates the transformation of image-based coordinates and data into world coordinates. Lastly, the resolution of the generated grid plays a vital role. This parameter dictates the step size for grid generation, specifying how many pixels to skip at each step.

The whole process is done in two steps.

First we read the height information into a two-dimensional matrix skipping the pixels as we mentioned before. Here is the code that creates this matrix:

Then we create a triangular mesh for the ground based on this matrix. Every element of the matrix is a point on the terrain with the points having a specific distance between them and the elevation being proportional to the value stored in the matrix. Here is the code that we use to generate the mesh:

// resolution is the number of pixels to skip as we read the image

int load\_heightmap\_image\_matrix(const std::string& filename, matrix<float>& m, int resolution) {

cg\_image img;

img.load(filename.c\_str());

int rows = img.height();

int cols = img.width();

unsigned char\* data = img.image();

if (!data) return 0;

m.resize(rows/ resolution, cols/ resolution);

// step is the number of bytes per pixel

int step = img.bytes\_per\_pixel();

for (int r = 0; r < rows; r += resolution) {

for (int c = 0; c < cols; c += resolution) {

// read alpha channel

m(r / resolution, c / resolution) = (data[(r \* cols + c) \* step + step - 1] / 255.0f);

}

}

return 1;

}

c\_mesh\* create\_heightmap\_mesh(const matrix<float>& hmap, float length\_scale, float height\_scale) {

c\_mesh\* ms = new c\_mesh;

auto cols = hmap.cols - 1; // goes into our x direction

auto rows = hmap.rows - 1; // goes into our z direction

// the edges of the terrain

float minx = -(cols \* length\_scale) / 2;

float maxx = (cols \* length\_scale) / 2;

float minz = -(rows \* length\_scale) / 2;

float maxz = (rows \* length\_scale) / 2;

int idx = 0; // counting the number of generated points

// texture coordinates for the terrain

float sx = 1.f / cols;

float sz = 1.f / rows;

float tx = 0;

float tz = 0;

for (auto z = 0; z < rows; ++z)

{

tx = 0;

for (auto x = 0; x < cols; ++x)

{

// x and z coordinates

float x1, x2, z1, z2;

x1 = minx + x \* length\_scale;

x2 = minx + (x + 1) \* length\_scale;

z1 = minz + z \* length\_scale;

z2 = minz + (z + 1) \* length\_scale;

// y coordinates (elevation)

float y1, y2, y3, y4;

y1 = hmap(z, x) \* height\_scale;

y2 = hmap(z, x + 1) \* height\_scale;

y3 = hmap(z + 1, x + 1) \* height\_scale;

y4 = hmap(z + 1, x) \* height\_scale;

// the four points

vec3 v1(x1, y1, z1);

vec3 v2(x2, y2, z1);

vec3 v3(x2, y3, z2);

vec3 v4(x1, y4, z2);

// the first triangle

ms->addVertex(v1);

ms->addVertex(v2);

ms->addVertex(v3);

ms->addIndices\_n(idx + 2, idx + 1, idx + 0);

// and the texture coordinates

ms->addTexCoord(tx, tz);

ms->addTexCoord(tx+sx, tz);

ms->addTexCoord(tx+sx, tz+sz);

idx += 3;

// the second triangle

ms->addVertex(v1);

ms->addVertex(v3);

ms->addVertex(v4);

ms->addIndices\_n(idx + 2, idx + 1, idx + 0);

// and the texture coordinates

ms->addTexCoord(tx, tz);

ms->addTexCoord(tx + sx, tz+sz);

ms->addTexCoord(tx, tz + sz);

idx += 3;

tx += sx;

}

tz += sz;

}

return ms;

}

All this is managed by this function:

gl\_prim\* create\_heightmap(const std::string& fname, float length\_scale, float height\_scale, int image\_resolution, GLenum drmode /\*= GL\_FILL\*/, bool dr\_el /\*= true\*/) {

matrix<float> hmap(1, 1);

load\_heightmap\_image\_matrix(fname, hmap, image\_resolution);

c\_mesh\* m\_hmap = create\_heightmap\_mesh(hmap, length\_scale, height\_scale);

gl\_prim\* p = new gl\_prim;

p->create\_from\_mesh(m\_hmap, drmode, dr\_el);

p->set\_texture(load\_texture(fname));

delete m\_hmap;

return p;

}

### Summary

In this part we covered the basics of OpenGL drawing. Now you are ready to create some nice programs and games, with nice visual effects. So far we have covered:

* Stencil buffers that can help us create irregularly shaped drawing areas.
* Blending, to simulate transparency.
* Face culling, to define back and front faces.
* Skyboxes to draw the horizon.
* Environment mapping that reflects the environment on the surfaces of objects
* Frame buffers to create dynamic textures.
* Shadows to add realistic 3D effects.
* Adding a fog effect to our scenes.
* Encoding terrain data in images with heightmaps.

## Part 7: Text

In the previous part we saw the need for text display in our games. From the simplest task to display some basic information to the user, to the display of a series of menu options for the user to select.

Displaying text from a simple program is easy. In C we have the *printf* function which prints text to the screen. As we saw in the first part of the book in C++ the equivalent id the *std::out* stream.

In complex environments though like OpenGL things are not so easy. Here we must create the objects that represent the characters we want to display.

The simplest way to display text is to create a texture image on which to draw all the characters of a font, and then use it to render quads with those characters. This technique relies on the things we have learned before about drawing with textures.

Here I am going to present a simpler technique that relies on the Windows system and generates a drawing list based on any system font. This drawing list can be used to render any text on the screen.

In the second part of this part, we will see how we can use the Windows system again to create a font with solid characters that can be used in any scene.

### 2D text rendering

I gave a brief description how to render 2D text on the screen using a texture. The technique we are going to see here is like that, only this time, most of the job is done by the system. It is Windows and OpenGL that do all the dirty work of creating the texture and generating the render commands required to draw each character.

First we generate a storage for the drawing commands for each character. This is the *list* that we generate which can store 256 characters. Then we ask Windows to generate a font as if we were going to draw some text on the screen. Finally, we instruct the Windows implementation of OpenGL to create the font textures and store the appropriate drawing commands in the character list we created.

HDC hDC = wglGetCurrentDC();

listBase = glGenLists(256);

if (strcmp(name, "symbol") == 0) {

hFont = CreateFontA(-size, 0, 0, 0, FW\_BOLD, FALSE, FALSE, FALSE,

SYMBOL\_CHARSET, OUT\_TT\_PRECIS, CLIP\_DEFAULT\_PRECIS,

ANTIALIASED\_QUALITY, FF\_DONTCARE | DEFAULT\_PITCH, name);

}

else {

hFont = CreateFontA(-size, 0, 0, 0, FW\_NORMAL, FALSE, FALSE, FALSE,

ANSI\_CHARSET, OUT\_TT\_PRECIS, CLIP\_DEFAULT\_PRECIS,

ANTIALIASED\_QUALITY, FF\_DONTCARE | DEFAULT\_PITCH, name);

}

SelectObject(hDC, hFont);

wglUseFontBitmaps(hDC, 0, 256, listBase);

Now that we have everything set up, we can use the font to render our text on the screen.

glColor4f(color2d.x, color2d.y, color2d.z, color2d.w);

glWindowPos2i(screenPos.x, screenPos.y);

glPushAttrib(GL\_LIST\_BIT);

glListBase(listBase);

glCallLists((GLsizei)strlen(text), GL\_UNSIGNED\_BYTE, text);

glPopAttrib();

Our font class has does not need a shader because it is only used to set the rendering color. OpenGL has several functions to do it. We set all four components of the color using *glColor4f* function which takes four floating point values, one for each color component. Then we do some housekeeping, by storing the current state of OpenGL before we activate the bitmap font storage and call it to render our text. Then we restore the state of OpenGL, and we return from the rendering function.

### 3D text rendering

Our next tool to display text is fancier. It creates three dimensional objects from the character description in the system font. This way we have real 3D objects that can be incorporated in our scenes like any other object we have seen so far.

The creation process of the 3D font is the same as the 2D font we saw earlier. The main difference when we generate 3D fonts is the function *wglUseFontOutlines* we call to generate the 3d objects. This function has two arguments that we need to pay some attention to.

The first is the *depth* of the character. These characters are created by extrusion, so we need to provide the depth. The second argument is the buffer that receives the dimensions of each character. We will need these dimensions when drawing the text.

HDC hDC = wglGetCurrentDC();

listBase = glGenLists(256); // create storage for 96 characters

if (strcmp(name, "symbol") == 0) {

hFont = CreateFontA(-size, 0, 0, 0, FW\_BOLD, FALSE, FALSE, FALSE,

SYMBOL\_CHARSET, OUT\_TT\_PRECIS, CLIP\_DEFAULT\_PRECIS,

ANTIALIASED\_QUALITY, FF\_DONTCARE | DEFAULT\_PITCH, name);

}

else {

hFont = CreateFontA(size, 0, 0, 0, FW\_NORMAL, FALSE, FALSE, FALSE,

ANSI\_CHARSET, OUT\_TT\_PRECIS, CLIP\_DEFAULT\_PRECIS,

ANTIALIASED\_QUALITY, FF\_DONTCARE | DEFAULT\_PITCH, name);

}

if (!hFont)

return;

SelectObject(hDC, hFont);

wglUseFontOutlines(hDC, 0, 255, listBase, (cg\_float)0.0f, (cg\_float)depth,

WGL\_FONT\_POLYGONS, gmf);

Since this font creates 3D objects we do not need a custom shader. Instead, we use the normal shader of our scene.

Our font class allows us to align the text at the bottom-left, bottom-center or bottom-right point. This requires us to calculate the length of the text prior to rendering to calculate how to place the text in our scene.

There is one thing we need to address when we render our text. Every character is a different object and must be positioned in the scene. So, we define a different *model* matrix for each one changing the translation matrix based on the alignment and stepping along as we move to the next character.

void cg\_font::render(cg\_shader\* shader, int alignment, const char\* str, ...) {

cg\_float length = 0;

char text[512];

va\_list args;

if ((str == NULL))

return;

va\_start(args, str);

vsprintf(text, str, args);

va\_end(args);

// center the text

// find length of text

for (unsigned int loop = 0; loop < (strlen(text)); loop++) {

// increase length by character's width

length += gmf[text[loop]].gmfCellIncX;

}

vec3 offset(0, 0, 0);

switch (alignment) {

case ALIGN\_CENTER:

offset.x = -length / 2;

break;

case ALIGN\_LEFT:

break;

case ALIGN\_RIGHT:

offset.x = -length;

break;

}

// draw the text

glPushAttrib(GL\_LIST\_BIT);

glListBase(listBase);

for (auto i = 0; i < strlen(text); ++i) {

mat4 ttm = tmat;

translate\_matrix(ttm, offset);

// putting translation at the end treats the text as a unit

mat4 ob\_matrix = rmat \* smat \* ttm;

shader->set\_mat4("model", ob\_matrix);

glCallLists(1, GL\_UNSIGNED\_BYTE, &text[i]);

offset.x += gmf[text[i]].gmfCellIncX;

}

glPopAttrib();

}

### Summary

In this part we addressed the rendering of text in OpenGL. However easy it may seem; we all know that text display is a major component in our communication with the user of our program.

We have covered the following.

* Two-dimensional text
* Three-dimensional text

## Part 8: Loading 3D Models in a Physics Simulation Application

The integration of 3D models into physics simulation applications has transformed fields like gaming, virtual reality, and scientific research. Whether we're developing a video game with realistic physics or simulating physical phenomena for academic purposes, loading 3D models correctly is crucial for ensuring accurate and engaging simulations. In this part we will go through the process of loading 3D models in our physics simulation application, covering key concepts, steps, and best practices.

### Understanding 3D Models and Physics Simulations

**3D Models:** 3D models are digital representations of objects or scenes created using specialized software. They consist of vertices, edges, and faces that define the shape and structure of the object. Common file formats for 3D models include OBJ, FBX, and STL.

**Physics Simulations:** Physics simulations involve the use of mathematical models and algorithms to replicate real-world physical behaviors. These simulations can include gravity, collisions, fluid dynamics, and more, providing a realistic interaction between objects within a virtual environment.

In this Part we will focus on loading and manipulating 3D models, leaving Physics Simulation for later.

### Importing 3D Models

To start we need to import our 3D models into our application. The exact process will depend on the software we are going to use, but the general steps will be as follows:

1. **Select a Compatible Format**: Ensure our 3D model is in the format required by our application (e.g., OBJ, STL). This means we must select a file format that best covers our needs. For example, if we want to perform simple physics calculations, geometric data is all we need, but if we are designing a game we need a lot of data about the object’s representation.  
   For most of the file formats we can find plenty of information or software libraries on the internet.
2. **Prepare the Model**: Clean up the model by removing unnecessary elements and ensuring it is optimized for our application. This includes checking for non-manifold geometry, applying transformations, and reducing polygon count if necessary.  
   This step is usually done in third party applications like Blender. In these applications we can create our models ar modify existing ones, to adapt them to our specific needs.
3. **Import the Model**: Create an import function within our application to load the 3D model. This may involve specifying import settings such as scale, orientation, and material properties.  
   Once our model has been brought to our specifications we can develop the necessary code to do this task.  
   After loading the model we create the meshes required for our calculations and drawing.

### Our implementation

The gl\_model class is designed to handle model loading in a straightforward and clear manner.

model1 = new gl\_model();

model1->load(model\_name);

model1->set\_scale(vec3(1,1,1));

In the *model\_loader* sample application we load the model and simply rotate and scale it using the mouse. The gl\_model class implements the necessary interfaces to perform these actions and finally draw the model as we did with all the simple objects so far.

Our library supports three model formats. They each have different characteristics and are very easy to implement. These formats are:

1. OBJ: this format supports material attributes and textures for model representations, making better for use in games and visualization applications.
2. STL: This format is very simple supporting only the geometry. This makes ideal for physics simulation and fast drawing.
3. OFF: This format enables per vertex color in the model making ideal for scientific representations of 3D models.

Sometimes the 3D modeling applications save the meshes in a clockwise order and we need to invert them to match the counterclockwise drawing we have. For this reason, we can ‘tell’ the loading mechanism to do the inversion by passing another argument either to the *constructor* or the *load* function.

### Summary

In this part we were introduced to the loading of 3D models in our application.

## Part 9: Adding a moving camera

Using a moving camera in physics simulations or games enhances user experience by providing dynamic perspectives, emphasizing key elements, and creating immersion. It offers flexible viewing angles and makes applications feel more realistic. In virtual or augmented reality, a moving camera with real-time visual effects greatly improves application quality and user engagement.

### Which computer programs need a moving camera

Many computer programs rely on moving cameras to provide dynamic perspectives, enhance user interaction, or simulate real-world scenarios. Here’s a breakdown of programs and software categories that often require moving cameras:

1. **Video Games**
   * 1. **Third-person action/adventure games** (e.g., The Legend of Zelda, Assassin’s Creed).
     2. **First-person shooters** (e.g., Call of Duty, Halo).
     3. **Racing games** (e.g., Forza Horizon, Gran Turismo).
     4. **Virtual/Augmented reality (VR/AR) applications** (e.g., Half-Life: Alyx, Beat Saber).
2. **Simulation and Training Software**
   1. **Flight Simulators** (e.g., Microsoft Flight Simulator, X-Plane): Moving cameras provide cockpit views and external perspectives.
   2. **Driving Simulators** (e.g., City Car Driving, Assetto Corsa): Cameras track vehicle movement and surroundings.
   3. **Medical Simulators**: Moving cameras simulate surgical procedures or patient interactions.

In summary, moving cameras are essential in programs that require dynamic perspectives, real-time tracking, or immersive experiences. These include game engines, 3D animation tools, simulation software, video editing programs, and many others across industries.

### Some common moving camera techniques

Depending on the application and its custom needs several techniques have been developed. Here are some of them:

1. **First-Person Camera**: The camera is positioned from the player's perspective, simulating what the character sees. This technique is common in first-person shooters and immersive exploration games.
2. **Third Person Camera**: The camera is placed behind and slightly above the player's character, providing a broader view of the surroundings. This technique is popular in action-adventure games.
3. **Follow Camera**: The camera follows the player's character, maintaining a constant distance and angle. This ensures that the character is always in view, regardless of their movement.

### How can we implement these camera techniques in games?

Implementing these camera techniques in games involves a combination of programming, design, and careful tuning to ensure they enhance the gameplay experience. Here’s a general overview of how developers can implement each technique:

1. **First-Person Camera**:
   * **Setup**: Position the camera at the character's eye level.
   * **Controls**: Link camera rotation to the player's mouse or right analog stick for looking around.
   * **Code**: Ensure the camera's position updates based on the character’s movement.
   * **Tips**: Consider adding a field-of-view (FOV) slider for player comfort.
2. **Third Person Camera**:
   * **Setup**: Position the camera behind and slightly above the character.
   * **Controls**: Use an orbit control system to allow the player to rotate the camera around the character.
   * **Code**: Implement collision detection to prevent the camera from clipping through objects.
   * **Tips**: Adjust camera distance and angles dynamically based on the environment.
3. **Follow Camera**:
   * **Setup**: Attach the camera to the character with a fixed offset.
   * **Controls**: Allow minor adjustments to the camera angle for player control.
   * **Code**: Smoothly interpolate the camera's position and rotation to follow the character.
   * **Tips**: Use damping to avoid sudden camera movements.

### Hands on approach

This tutorial covers two types of moving cameras. First, we will create a First-Person Camera, where the camera represents the user's eyes. Second, we will create a Third Person Camera that follows the action from a distance.

We developed a car simulation application to demonstrate these concepts. You can drive the car in a virtual city, switch between the driver’s view and the following camera, and observe the differences between the two camera types.

#### The basics

In our examples, we use a viewport and camera to handle perspective, as detailed in Part 4 of this tutorial. For our moving camera, we will rely on these objects:

* The `gl\_viewport` class controls the viewing volume.
* The `gl\_camera` class holds the viewer's position and orientation.

The viewer controls the camera's movement and tilt. Position is determined by the `*vLocation*` variable, and orientation by the view direction `*vForward*` and the up-pointing vector `*vUp*`. Our camera already supports all the necessary functionality for the moving camera concept.

#### First-person camera

For the first-person camera, the camera is positioned at the center of the car and moves together with the car. The car's velocity vector is normalized to determine the forward direction of the camera. The global ‘y’ axis represents the upward direction for the viewer/camera. As the position and orientation of the car are updated, the driver's point of view is also updated accordingly.

#### Third-person camera

This camera is programmable with various effects achievable from a third-person perspective, enhancing user engagement in the application.

Consider a camera mounted on a virtual drone that can initially be placed anywhere in the simulated environment. A point is selected at a specific distance behind the car, designated as the target position for the drone. This target point continuously updates as the car moves.

The drone, carrying the camera, flies to this updated target position while ensuring the camera always focuses on the car. This method ensures a smooth transition for the camera and perspective.

### Summary

In this part we covered the need for a moving camera in our application and how we can create one.

## Part 10: Understanding Flight Simulators and How to Create One

Flight simulators are essential tools used for training, entertainment, and research. They have evolved from simple models to highly sophisticated systems.

A flight simulator replicates an aircraft’s controls and environment, providing a virtual flying experience. Initially developed for pilot training, they now serve various purposes, including entertainment, research, and emergency procedure training. This article explores flight simulators, their purpose, and offers a guide on creating your own.

### What is a Flight Simulator?

A flight simulator is a system that mimics the physics, controls, and behavior of an aircraft.

Flight simulators model an aircraft’s cockpit, instruments, and flying environment, allowing users to interact as if they were piloting a real aircraft.

### Types of Flight Simulators

* **Full Flight Simulators (FFS):** High-fidelity simulators used by professional pilots for training, featuring motion platforms, visual displays, and comprehensive controls.
* **Fixed-Base Simulators (FBS):** Used for training without the motion component.
* **Desktop Simulators:** Accessible on personal computers, popular among aviation enthusiasts for entertainment or casual training.

### Applications of Flight Simulators

* **Pilot Training:** Primarily used for pilot training, helping pilots practice flying in various weather conditions, emergency scenarios, and complex airspace systems.
* **Entertainment and Gaming:** Popular in the gaming community, allowing users to experience the thrill of flying.
* **Research and Development:** Used by aircraft manufacturers and the aviation industry for testing aircraft designs, flight dynamics, and safety features.
* **Public Education:** Utilized in aviation museums and educational facilities to introduce people to the basics of flight.

### How to Write a Flight Simulator

This section outlines the key steps involved in creating a simple flight simulator, from planning to implementation.

#### Define the Scope

Decide on the complexity of your simulator. Are you creating a basic 2D flight simulation or a full 3D simulation with advanced physics? Determine whether the simulator will focus on specific aircraft types, flight dynamics, or a broad range of general aviation aircraft.

#### Choose Your Tools and Platform

* **Programming Language:** Most flight simulators are written using languages such as C++, Java, or Python due to their performance and flexibility.
* **Graphics Engine:** Use a graphics engine like Unity3D, Unreal Engine, or OpenGL for rendering 3D environments.
* **Flight Simulation Libraries/Frameworks:** Utilize open-source frameworks like FlightGear, X-Plane SDK, or SimConnect (for Microsoft Flight Simulator) to streamline the development process.

#### Design the Flight Physics and Environment

* **Flight Dynamics:** Accurate flight physics are crucial. Research aerodynamics principles to simulate lift, drag, thrust, and weight. Tools like OpenFlight and JSBSim can assist with this.
* **Aircraft Models:** Build or obtain detailed models of the aircraft you wish to simulate, including both the external shape and internal cockpit controls.
* **Environment Modeling:** Design the landscape, airports, runways, weather patterns, and time of day. Use elevation data for terrain and satellite imagery for realistic environments.

#### Create the Cockpit Interface

Design the cockpit with all necessary controls, displays, and instruments (e.g., altimeter, artificial horizon, speed indicator). This involves user interface (UI) programming and interaction design.

#### Add Interactivity and Controls

Program the flight controls, such as the yoke, throttle, pedals, and other input devices. Implement support for real-world flight control hardware (joysticks, yokes, and pedals). Use input handling libraries for keyboard, mouse, or controller inputs and link them to the simulator’s actions.

Testing and Refining

Test the simulator extensively, focusing on fine-tuning the user experience, flight physics, and overall performance. Identify and fix bugs, glitches, or unrealistic behavior. Ensure the simulator performs well on various devices.

Key Considerations for Advanced Flight Simulators

* **Realism:** Strive for realism in flight dynamics, aircraft systems, and scenery. Implement features like realistic weather conditions, autopilot systems, and engine performance.
* **Multiplayer and Networking:** Add networking capabilities for users to fly together in a shared virtual environment. Implement multiplayer functionality and data synchronization for real-time interaction.
* **VR and Motion Sensing:** Integrate VR compatibility for an immersive experience. Motion-sensing devices can simulate the physical experience of flying, adding realism.

Flight simulators are powerful tools that have transformed pilot training, aircraft development, and aviation engagement. Whether for professional use, entertainment, or research, building a flight simulator is a rewarding challenge. With the right tools, dedication, and understanding of flight dynamics, anyone can start developing their own simulator. As technology evolves, the possibilities for flight simulation are limitless.

This structure provides a clear flow for your article, starting with an introduction to flight simulators, followed by a step-by-step guide on creating one, and finishing with a discussion of advanced features. Adjust the details according to your audience, whether they are beginners or experienced programmers!

### The basic parts of the airplane

A diagram of a plane

AI-generated content may be incorrect.**Fuselage**: The body of the airplane

**Wings**: The generally flat structures that generate the lift which make the airplane fly

**Tail**: The back of the airplane which consists of a vertical and a horizontal section. Its main role is to stabilize the airplane.

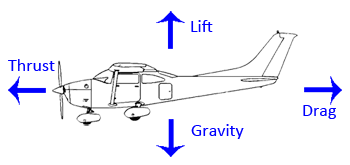
**Ailerons**: Movable areas on the outer part of the wings, used to make the airplane roll.

**Flaps**: Movable areas at the inner part of the wings, used to increase lift at low speeds and drag.

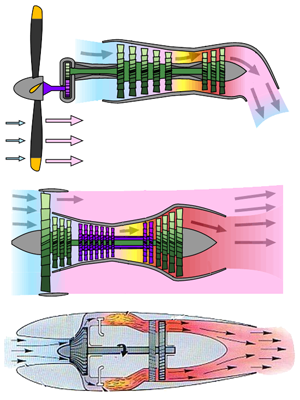
**Elevators**: Movable areas of the horizontal tail section used to control pitch.

**Rudder**: Movable area of the vertical tail

### Forces acting on an airplane

The primary force acting on any object is gravity. To achieve flight, we need to generate an equal and opposite force known as lift, which is produced by the wings as the airplane moves forward. This movement is driven by thrust, and due to aerodynamic resistance, we encounter a force opposing the movement called drag. Gravity is the existing force, while thrust is the force controlled by humans. Lift and drag are the outcomes of the airplane's movement.

### What makes the airplane move?

We begin our journey with the primary force we generate on the airplane: thrust. Thrust is the energy source that airplanes need to create lift and ultimately achieve flight. Gravity, one of the fundamental forces of nature, is always present. However, to generate lift, we must make the airplane move, and thrust accomplishes this.

So, what exactly is thrust and where does it come from?

Thrust is the force produced by the engine that propels the airplane forward. There are various methods to convert the mechanical energy generated by the engine into thrust. The oldest method involves a propeller attached to the engine's drive shaft, while the most modern method uses jet engines.

In the image, we can see the three basic types of thrust generators designed for larger airplanes that require more power. For smaller airplanes, the propeller is powered by smaller reciprocating engines instead of turbines.

The first type of engine is the turboprop, the second is the turbofan, and the third is the jet engine. Delving into the working details of these engines is beyond the scope of this article.

### Lift and Drag, how are they generated?

We understand that lift is a result of the airplane's movement due to thrust. Let's delve deeper into what happens when the airplane moves.

Diagram of a diagram showing the lift and extended flap

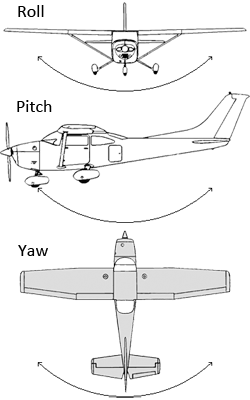
AI-generated content may be incorrect.Any object moving within a fluid, such as air, generates two forces. One force, called drag, opposes the direction of movement and is proportional to the object's size, shape, the fluid's viscosity, and the square of the object's speed. The other force, perpendicular to drag, is known as lift. The magnitude and direction of lift are determined by the shape and orientation of the airplane's main surfaces, primarily its wings. A poorly designed airplane might generate negative lift, which is desirable in sports cars.

How is lift generated? The wings' shape causes the air above the wing to move faster than the air below it, creating a pressure difference that results in lift. Another crucial factor is the "angle of attack," which is the angle between the wing's longitudinal axis and the airplane's direction.

However, things are not so simple. Modifying the wing's shape to generate more lift also increases drag. If the angle of attack is increased too much, the airflow over the wing becomes turbulent and detaches, raising pressure and reducing lift.

Therefore, we need a mechanism to alter the wing's shape and generate significant lift at low speeds for quick takeoff and slow-speed landing approaches. This mechanism is the flaps. The flaps extend and move downward based on the pilot's decision. Extending the wings in this manner generates the necessary lift at low speeds to keep the aircraft airborne. As airspeed increases, the pilot retracts the flaps since the wing can generate the required lift without additional assistance.

### Movements of the airplane

To navigate the airplane to the desired location, the pilot uses the controls to perform one of three movements shown in the image.

Roll: This is the rotation around the airplane's lengthwise axis (from nose to tail). It's controlled by the ailerons, which are small flaps on the wings. When one aileron goes up and the other goes down, the airplane rolls to the side.

Pitch: This is the rotation around the airplane's side-to-side axis (from wingtip to wingtip). It's controlled by the elevators, which are flaps on the tail. When the elevators go up, the nose of the airplane goes up, and when they go down, the nose goes down.

Yaw: This is the rotation around the airplane's vertical axis (from top to bottom). It's controlled by the rudder, which is a flap on the tail. When the rudder moves left or right, the nose of the airplane turns in that direction.

Combining these movements allows the pilot to steer the airplane in different directions.

How does the airplane respond to these movements? To understand this, we need to analyze how the control surfaces influence the airplane and cause it to move. When a control surface like an aileron moves, it diverts the airflow around it, creating a force. These forces generate torques around axes that pass through the airplane's center of gravity. Summing up all these torques gives us the final torque that changes the airplane's orientation.

We can assume that the airplane itself is a rigid body. Although we have seen airplane wings vibrating during flights, indicating they are not entirely rigid, we can ignore this for our simulator. Therefore, we only need to know the airplane's total inertia, which is the sum of the local inertia of its elements, such as the fuselage, wings, flaps, ailerons, and rudder.

### Creating the simulator

Delving into the physics model of a flight simulator is beyond the scope of this article. My aim is to provide a simple overview of what is involved in creating the simulator. The airplane's physics model was originally developed by David M. Bourg in his book "Physics for Game Developers" (ISBN: 0-596-00006-5 © O'REILLY 2002). This book is an excellent resource for understanding game physics. The beauty of physics is that it remains relevant over time, so if you can find a copy, I highly recommend reading it.

The simple simulator we created divides the screen into two areas. The top section displays the view from the pilot's window, while the bottom section is the instrument panel. The instrument panel A screenshot of a video game

AI-generated content may be incorrect.consists of a map of the world with the airplane always centered and pointing upwards. This view is essentially the same as the top view but from a different perspective. On the left side, you will see five instruments: the artificial horizon, the roll indicator, the compass, the altitude-speed-climb rate indicator and the throttle and stick position.

The stick that controls the ailerons and elevators is operated by the mouse. Moving the mouse up or down operates the elevators, while moving it right or left operates the ailerons. The throttle is controlled by the 'A' and 'Z' keys. The simulator is quite simple, and the scenery is not very detailed. There is no takeoff or landing procedure, and the action starts in the air. No collision detection is performed, and the earth is flat and limited. The visual effects developed in previous articles are included, and the airplane physics are modeled effectively.

In this sample we make extensive use of all the thins we discussed so far. We have multiple views and cameras, we perform scissor tests to limit the extension of our drawing and so on.

### Summary

In this part we saw some elements of a real-world game/simulation application where we used most of the techniques we developed so far.